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RADOME BORESIGHT ERROR ASSESSMENT AND SYSTEMS
EVALUATION TEST CHAMBER IMP. (U) ALABAMA UNIV IN
HUNTSVILLE SCHOOL OF ENGINEERING P A TILLEY ET AL.

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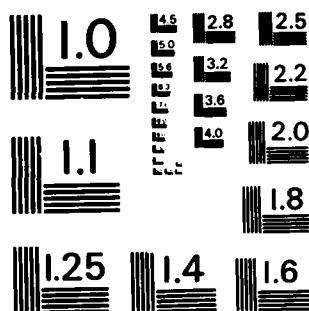
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TECHNICAL REPORT RD-CR-83-16

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RANDOM BORESIGHT ERROR ASSESSMENT AND SYSTEMS
EVALUATION TEST CHAMBER IMPROVEMENTS

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April 1983

Prepared for
System Simulation and Development Directorate
US Army Missile Laboratory



U.S. ARMY MISSILE COMMAND

Redstone Arsenal, Alabama 35898

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20. ABSTRACT (Continue on reverse side if necessary and identify by block number) Accomplishments in radome testing and analysis were continued through performance of the task documented by this report. Software improvements for the Radome Positioner and the Radome Measurements Receiver System are presented. The radome testing and post-processing of data are described. Testing and processing difficulties are also discussed.		

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PREFACE

This technical report was prepared by R. G. Gean, P. A. Tilley, and T. A. Palmer, Electrical and Computer Engineering Department, School of Engineering, The University of Alabama in Huntsville. The purpose of this report is to provide documentation of the technical work performed and of results obtained under delivery order number 0006, contract number DAAH01-82-D-A008; Dr. N. A. Kheir, Principal Investigator. Dr. M. M. Hallum, III, Chief, System Evaluation Branch, Army Missile Laboratory, U.S. Army Missile Command, was technical monitor. Mr. Ernst Evers-Euteneck of the Systems Evaluation Branch provided technical coordination.

The authors wish to acknowledge the valuable discussions and assistance provided throughout the task by L. Ragland of the Systems Evaluation Branch and C. Adams of the Aeroballistic Analysis Branch.

The technical viewpoints, opinions, and conclusions herein are those of the authors and do not imply policies or positions of the U.S. Army Missile Command.

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1.0 INTRODUCTION

The purpose of this report is to review the work performed and the results obtained since completion of the previous delivery order reported in [1]. The goal of this work was to provide a statistical evaluation of IHAWK radomes. The areas of work performed include System Evaluation Test Chamber (SETC) preparations, radome measurements, and data processing.

Section 2 of this report will present the hardware and software changes incorporated to improve the accuracy of data. Changes in test methods, the Radome Positioner software, and the Radome Measurements System software resulted in improved accuracy by improving the acquisition process. The actual tests performed and the results of those tests are found in Section 3 while Section 4 provides a description of the processing means used to analyze and to plot data. Section 5 presents an outline of the major problems and difficulties encountered during performance of the task. Conclusions and recommendations for possible future improvements are presented in Section 6.

2.0 SYSTEM EVALUATION TEST CHAMBER (SETC) PREPARATION

2.1 Introduction

SETC preparations continued throughout this task and included reconfiguring the hardware for each entrance to the SETC. This was essential since several groups share the SETC and each requires a different configuration.

A Modification to the test configuration was made by using an offset transmitter horn configuration to induce a known error. The error must stay sufficiently large for the network analyzer to register a stable phase measurement. Another SETC modification consisted of new software written in Motorola 6800 assembly code and Fortran for the Radome Positioner and Radome Measurements Receiver System. This software provides improved operating systems which produce more usable, more complete data sets.

2.2 Phase Offset

Phase offsets measured by the network analyzer provide the signs of error when plotting data. For radomes with very small boresight errors the network analyzer could not provide a stable phase measurement. Thus, a need existed to find a method to accurately test radomes with the available equipment.

Studying the problem led to offsetting the transmitting horn by a known amount. The receiving antenna was boresighted on this offset horn. After boresighting, the transmitting horn was returned to its original center position and scans were executed. Using this method, an inherent error (the amount of offset), which is of a magnitude large enough for the network analyzer to operate accurately, exists. This offset is later removed during data processing to reveal the true magnitude and phase of the boresight error. The arrangement of the transmitting horn is illustrated in Figure 1.

2.3 Software Improvements

Software improvements were made to both the radome positioner operating system and the radome measurements receiver system. Improvements in the positioner are discussed in Section 2.3.1, and those for the measurements receiver are discussed in Section 2.3.2.

2.3.1 Radome Positioner Improvements

A procedure has been developed for easy modification of the Radome Positioner operating system. Working from previous documentation, source files have been reconstructed and stored on master source file diskettes with a Tektronix 8002a microprocessor development system. Using these source files, the positioner program can be modified and recompiled as needed. Subsequently, PROMs can be programmed with modified programs and inserted into the M6800 based microcomputer which controls the positioner.

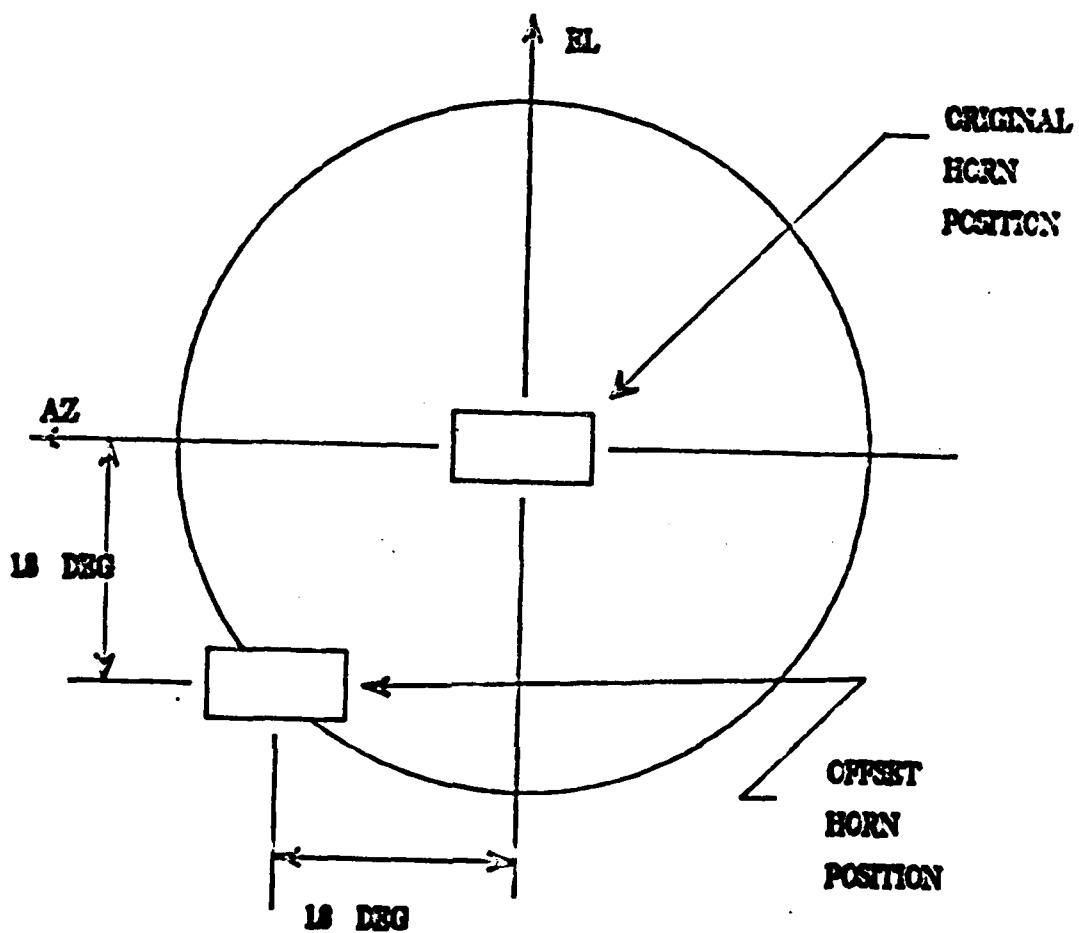


FIGURE 1 TRANSMITTING HORN ARRANGEMENT

Presently, all modifications are implemented using the Tektronix 8002a. However, the source files could be transferred to any other 6800 Development System.

Using the method described above, a new scan pattern has been implemented on the positioner. The previous positioner patterns were not adequate for thorough analysis of radome boresight error and antenna pattern measurements. This inadequacy existed because the area covered by the scan was not sufficient to yield the full scope of information about the antenna or radome. A careful analysis of the type of data needed revealed that the scan pattern illustrated in Figure 2 was the most useful pattern. The two most pertinent reasons were that (1) the shape of the radome suggested a circular window and (2) the method of data analysis intimated a raster-type scan.

The new pattern covers all data points necessary for current boresight error analysis and antenna pattern measurements. Execution of the pattern (number 3) requires the following key-in sequence:

```
PROG 3
32.0
1.0
```

where 32.0° is the radius of the circular scan region and 1.0 is the number of degrees between each azimuth scan. The revised operating system is presented in Appendix B.

2.3.2 Radome Measurements Receiver System Improvements

A procedure has been developed for modification of the Radome Measurement Receiver System operating system. Previously, it was believed that all calculations associated with radome boresight error and antenna pattern measurements could be done during "real-time" operation. However, it was determined that the receiver could not sample each point, perform all of the required calculation, and store the results before the radome reached the next sample point for the density of data desired. All of the calculation routines have therefore been removed from the operating system. This resulted in a more than 60% decrease in the total size of the object code file. In addition to this reduction, the FORTRAN main routine was decreased in size causing another 10% reduction of the total operating system size.

Previously, it was necessary for the operator to interact on a machine level in order to select a sample size. This interaction has been eliminated by enabling the FORTRAN main routine to pass the variable to the assembly routine, CNTL. Modifications have been made to CNTL to enable the receiver to sample on integer degrees within $\pm .043945^\circ$. This is important for precise calculations of boresight error slopes. The revised software is presented in Appendix C.

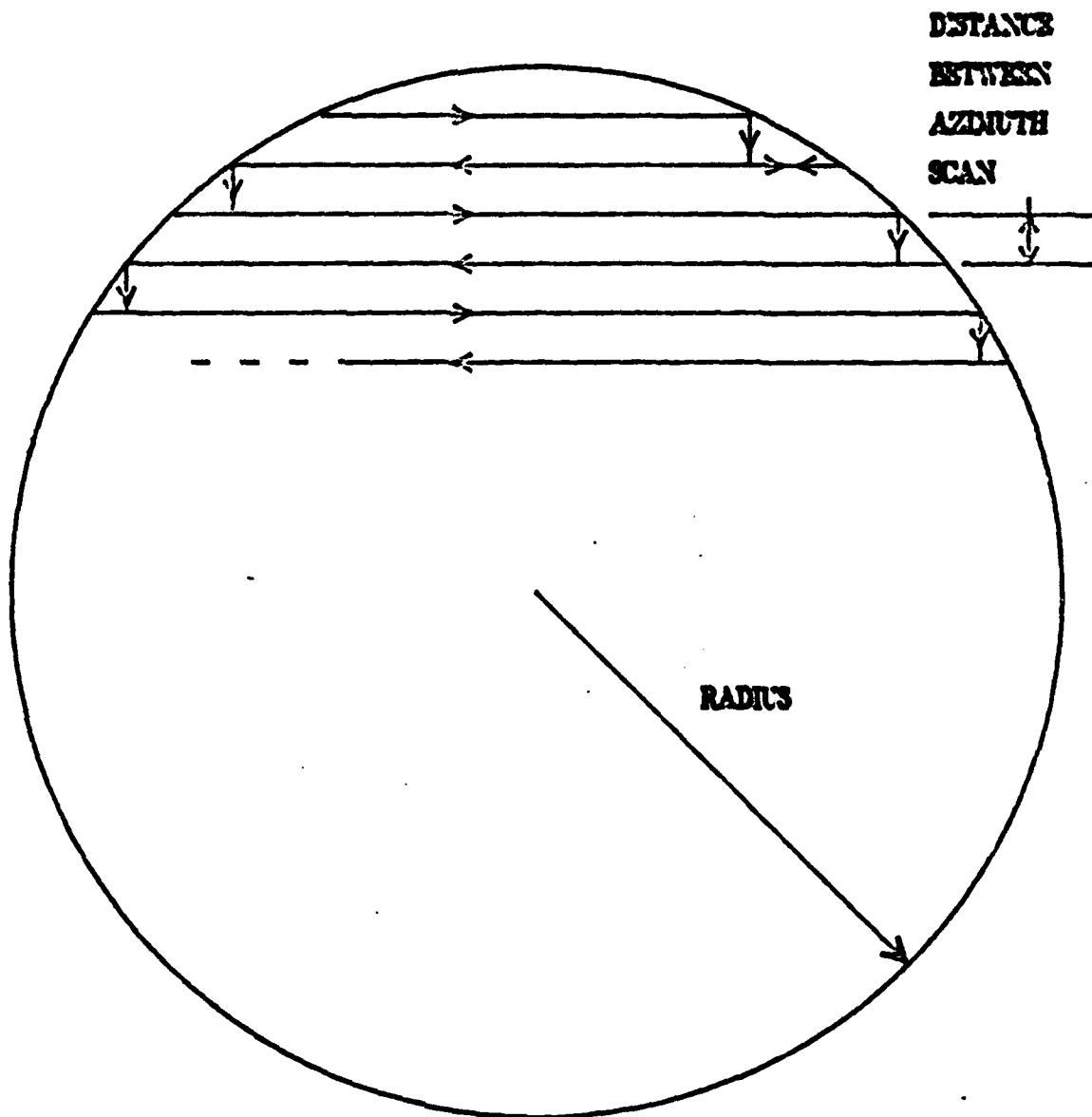


FIGURE 2 RASTER SCAN PATTERN

3.0 SETC TESTING

3.1 Introduction

The majority of tests covered by this report are tests which have been repeated using the induced offset described in Section 2.2. The tests fall into three groups: (1) acceptable radomes, (2) obstructed radomes, and (3) no radome.

3.2 GROUP 1 - Acceptable Radomes

This group of radomes include those which have passed final quality assurance inspections. Twelve IHAWK radomes in this category were tested. These tests were repeats of prior tests which did not use the induced offset test method. Vector plots obtained after removal of the known bias show uniformly distributed errors. The largest boresight errors are slightly in excess of one-half degree. The areas of least boresight error occur along the azimuth and elevation axes. Examples of these plots are presented in Figures A-1 through A-5 in Appendix A.

3.3 GROUP 2 - Obstructed Radomes

In an effort to better understand the offset horn configuration, an IHAWK radome was tested using a plexiglass obstruction. The purpose of this test was to observe the effect of the offset method on the large errors caused by placing an obstruction in the radome. Plots show that all errors not affected by the blockage are pointing toward the center of the radome. However, azimuth errors affected by blockage are pointing away from the center. The reason for this deviation may be a change in the polarization of the signal as it passes through the obstruction. Plots of this data are also included in Appendix A in Figures A-6 through A-10.

3.4 GROUP 3 - No Radome

Two tests were performed with no radome attached to the gimbal. The first test was run using the standard horn configurations. The purpose of this test was to check the testing equipment and the anechoic chamber; also, this test served as a comparison for the second test with no radome. The second test was made without a radome but with the horn positioned using the offset bias. This test was then compared with the previous test to detect any inconsistencies between the two configurations. The results of both tests were satisfactory with each showing only negligible errors.

4.0 DATA PROCESSING

4.1 Introduction

This section reviews the methods used to provide analysis of the data obtained during radome tests. The plotting programs and the statistical analysis program are discussed. Additionally, the method used to remove the induced bias are explained.

4.2 Removing Offset

With the configuration illustrated in Figure 1 and the dimensions of the anechoic chamber, there exists an offset of approximately 1.8° in both azimuth and elevation. Since exact positioning of the offset horn is unrealistic, the exact position can only be said to be within $\pm 0.1^\circ$ of the desired value. The error, looking through the center of the radome, should be zero, and the overall average should also be zero. Thus, the average of all errors can be subtracted from each data point to compensate for small errors in alignment. Since the offset error is simply added to the true error, the total average of all errors is subtracted from each data point to compensate for both small errors in alignment and the $\pm 0.1^\circ$ unknown offset error.

The average value is subtracted from each point of raw data with the result being stored in a new file containing the true boresight error for each set of azimuth and elevation angles. Data can then be retrieved by one or more of the plotting programs described in the following section. Plots of the data reflect the true boresight error values.

4.3 Plotting Programs

The two types of plots produced during this task were boresight error vector plots and boresight error three-dimensional plots. Minor adjustments to the existing vector plotting program allowed this program to access the file which contained data with the offset removed. These vector plots display azimuth and elevation errors in the form of a pointing vector emanating from a footpoint which is placed at integer values of azimuth and elevation angles.

Also utilized were two variations of the three-dimensional plotting routines. The first variation was the CARPET program which is normalized and produces a three-dimensional plot with all points connected by lines. The second was the program, CARPET 2, which is the same as CARPET except that it removes the lines which should be hidden, producing an easily readable plot. Examples of these plots are included in Appendix A, and a more detailed description of the actual plotting programs can be found in [1].

4.4 Statistical Analysis

The same methods of statistical analysis described in the report "Radome Boresight Assessment" [1] were utilized during this task. Data collected in the radome tests has been stored to facilitate rapid statistical analysis.

5.0 TESTING AND PROCESSING DIFFICULTIES

5.1 Introduction

Fewer difficulties arose during this task than during previous tasks. However, the following equipment and phase coordinate problems are considered significant.

5.2 Equipment Problems

At the beginning of the testing period, two radomes were tested and analyzed with the results being acceptable. Based on these results, the remaining tests were conducted prior to plotting and analyzing the data. This was required due to time limitations in the SETC. After testing was completed, discrepancies in phase were discovered in the last nine sets of data. This problem was traced to a phase line being grounded. After this problem was corrected, it was necessary to repeat the tests which yielded unacceptable data. Repeated tests provided acceptable results.

Another topic for discussion in this section is the computer system available for radome analysis. Although there has been a significant decrease in down time, terminal access remains a problem. Inavailability of terminals connected to the system has caused several delays.

5.3 Phase Coordinate System

Processing statistical evaluations of several sets of raw data unexpectedly revealed overall boresight averages with a negative azimuth value and with a positive elevation value. Since this was not expected while using the offset method described in Section 2.2, investigations to find the cause were conducted.

The problem was eventually solved by showing that the test equipment is arranged in a manner which logically reverses the apparent error during the test. For an observer positioned behind the antenna and looking in the direction of R_a (see Figure 3), a positive pitch (elevation) error indicates that the actual target location is above the R_a axis, as expected. However, a positive yaw (azimuth) error indicates that the actual target location is to the left of R_a in the yaw plane [2].

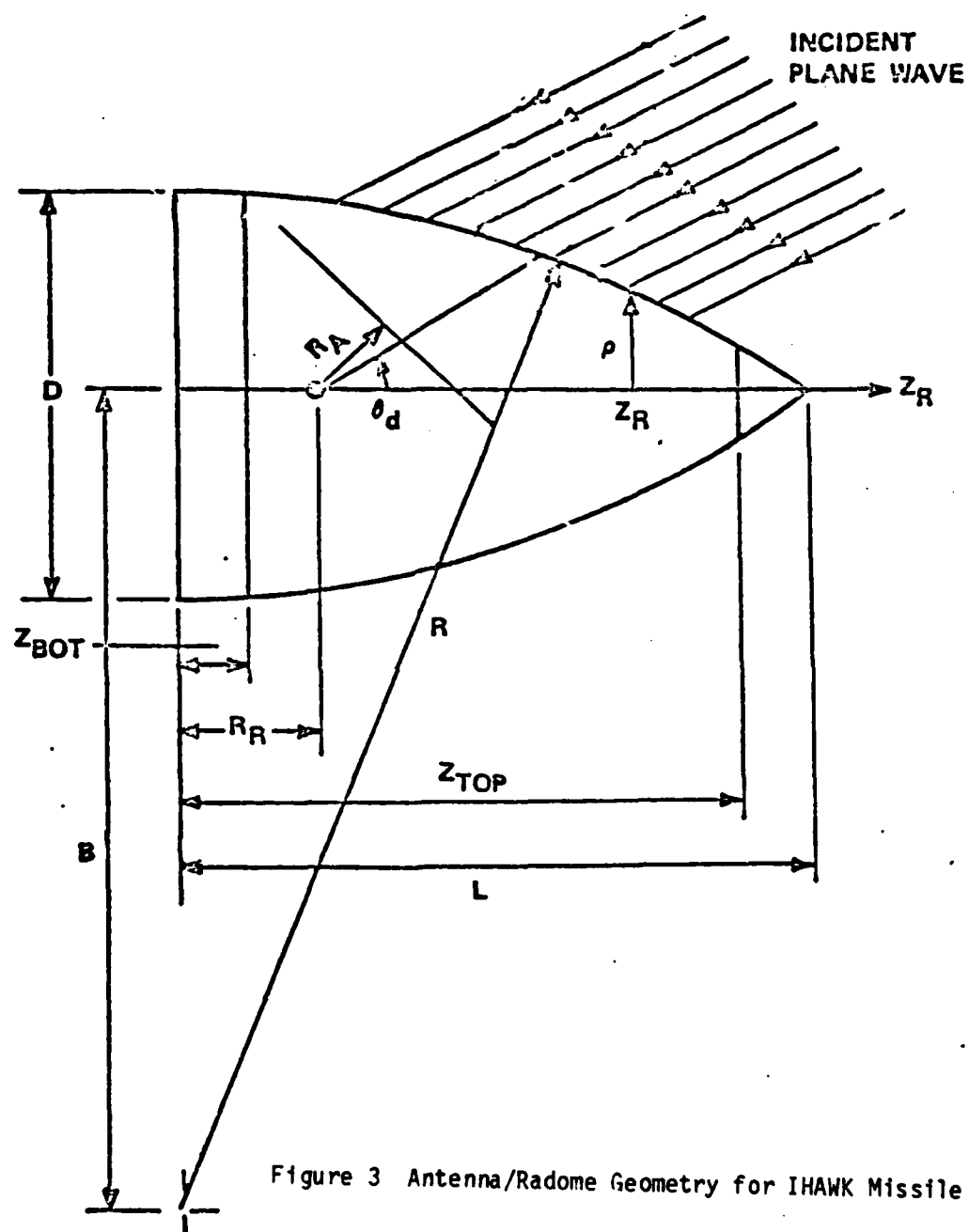


Figure 3 Antenna/Radome Geometry for IHAWK Missile

6.0 CONCLUSIONS AND RECOMMENDATIONS

Plots resulting from the use of the new offset horn method are accurate, readable, and present a better overall representation of the true boresight error induced by the radome. Software improvements have proven to be reliable and time-saving tools aiding in the performance of radome testing. Due to these software improvements, the possibility now arises to study boresight error slopes. Boresight error slope is an important characteristic since it indicates the rate of change of the boresight error. Knowledge of this rate is significant for missile response since it can be used to predict future boresight errors by utilizing the information of target movement.

The majority of the recommendations presented in [1] have been implemented. A time-saving recommendation repeated here is the need for a means to transfer data directly from the test system's floppy disks to the data processing system. This modification would also eliminate the need to acquire data cassette tapes. Other recommendations include improved plotting capabilities (possibly on site) and the acquisition of a graphics terminal dedicated to radome testing.

REFERENCES

- [1] Tilley, Patrick A. and Gean, Roger G., "Radome Boresight Assessment," UAH Technical Report #82/10, Contract #DAAH01-82-D-A008, Delivery Order #0006, prepared for the Systems Simulation and Development Directorate, U. S. Army Missile Command, Redstone Arsenal, AL, October 1982.
- [2] Bassett, H. L., Hallum, M. M., Handley, J. C., Harris, J. N., Huddleston, G. K., Letson, K. N. and Yost, D. J., "Radome and Irdome Technology, A Short Course of Instruction," sponsored by U.S. Army Missile Command, Redstone Arsenal, AL, November 1982.

Appendix A
Boresight Error Plots

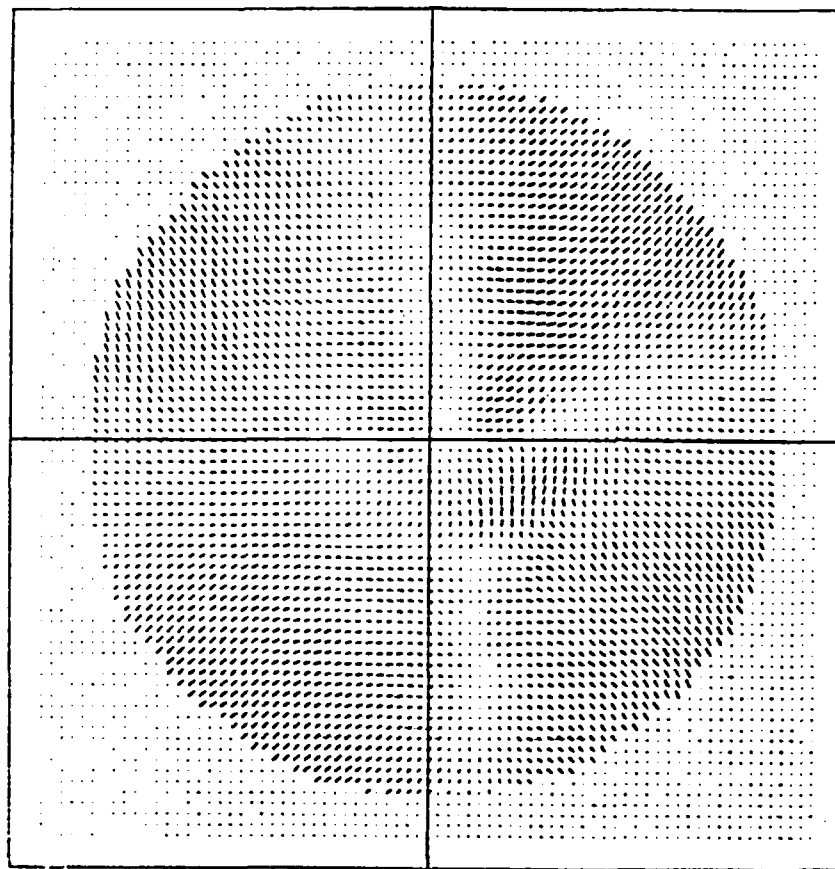


Figure A-1
 Vector Plot of Boresight Error for Acceptable IHAWK Radome - Case I
 (Scale: Distance between dots = $\frac{1}{2}^\circ$ of error = 1° of position)

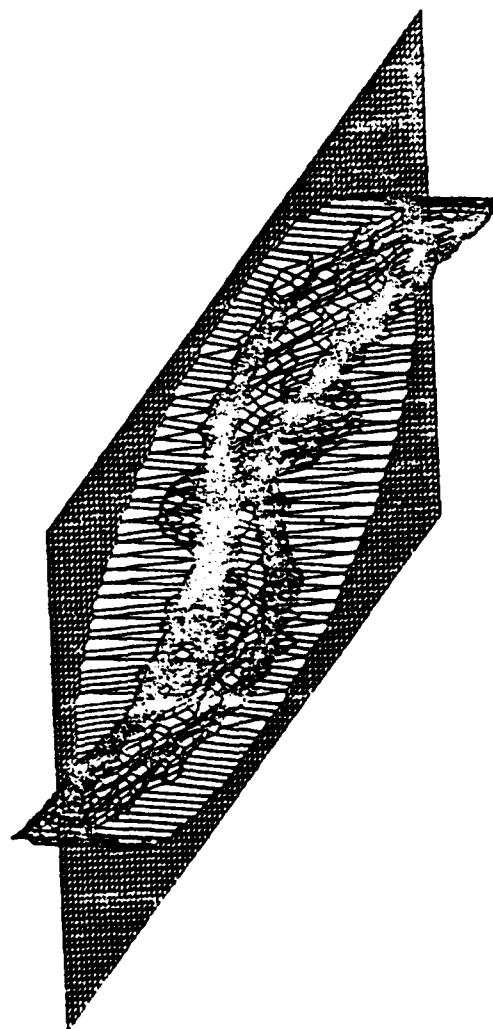


Figure A-2
Carpet Plot of Azimuth Error for Case I

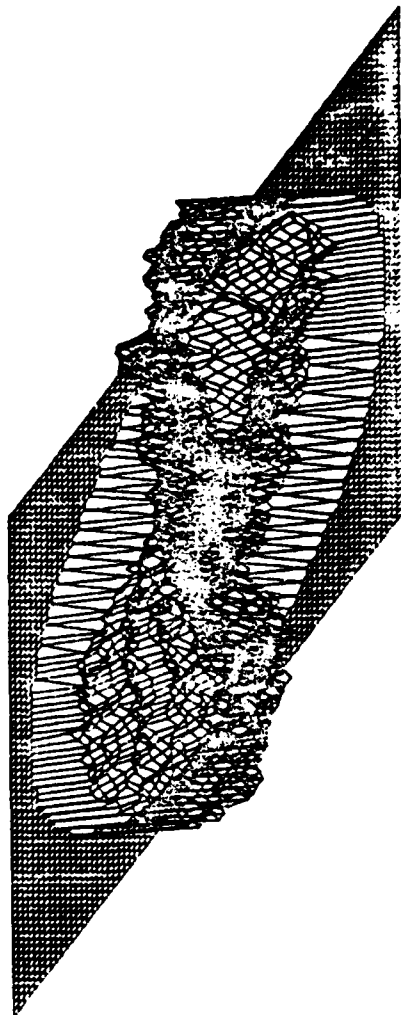


Figure A-3
Carpet Plot of Elevation Error for Case I

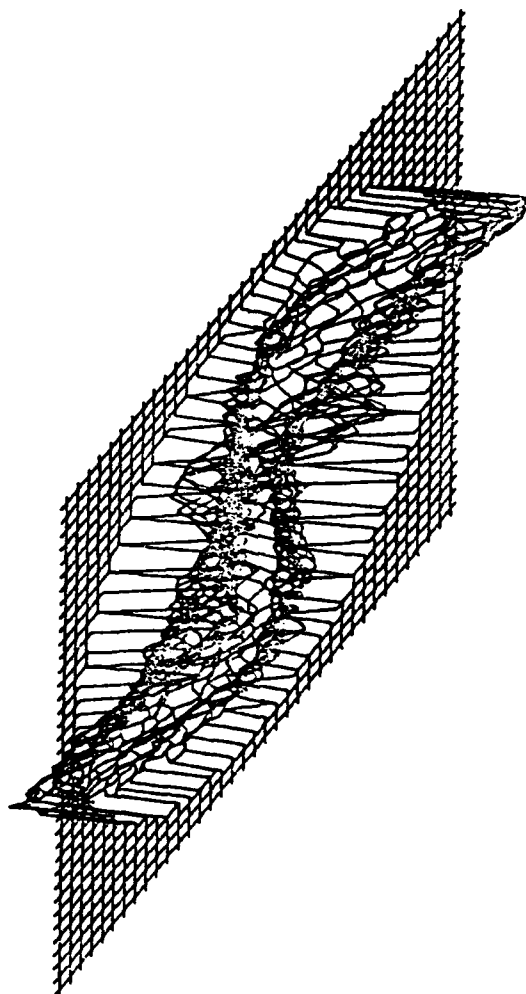


Figure A-4
Carpet II Plot of Azimuth Error for Case I

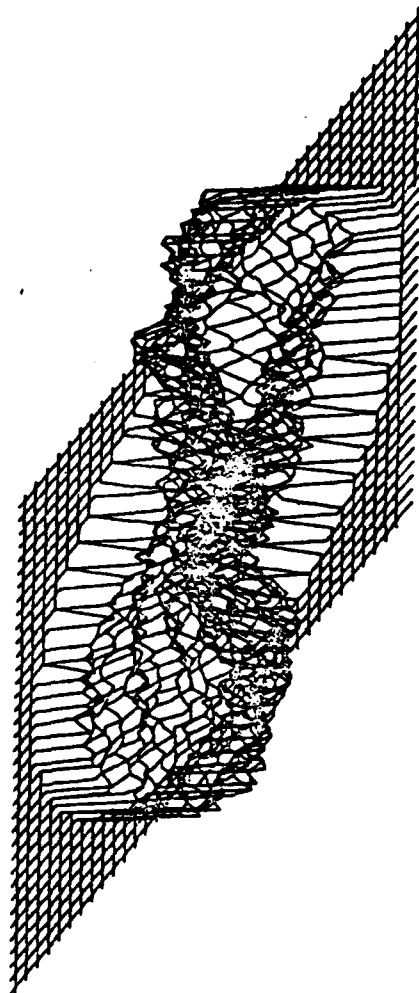


Figure A-5
Carpet II Plot of Elevation Error for Case I

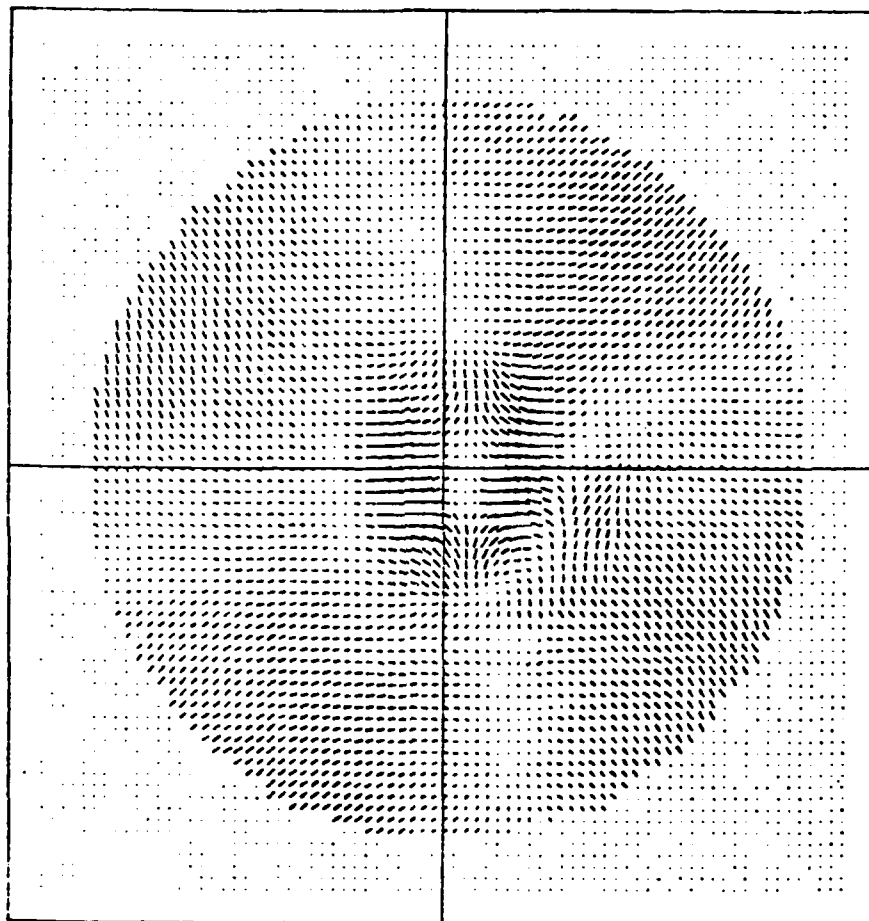


Figure A-6
Vector Plot of Boresight Error for Radome with Plexiglass Obstruction - Case II
(Scale: Distance between dots = $\frac{1}{2}^\circ$ of error = 1° of position)

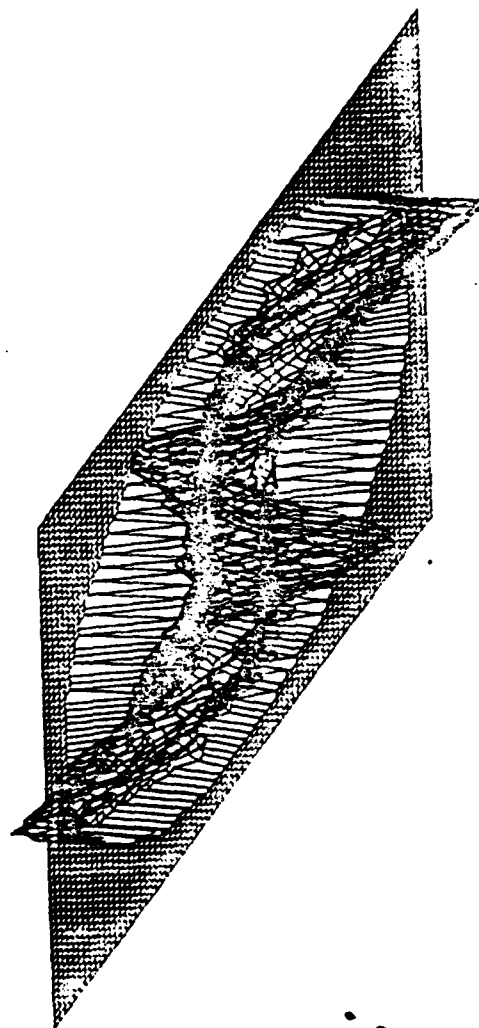


Figure A-7
Carpet Plot of Azimuth Error for Case II

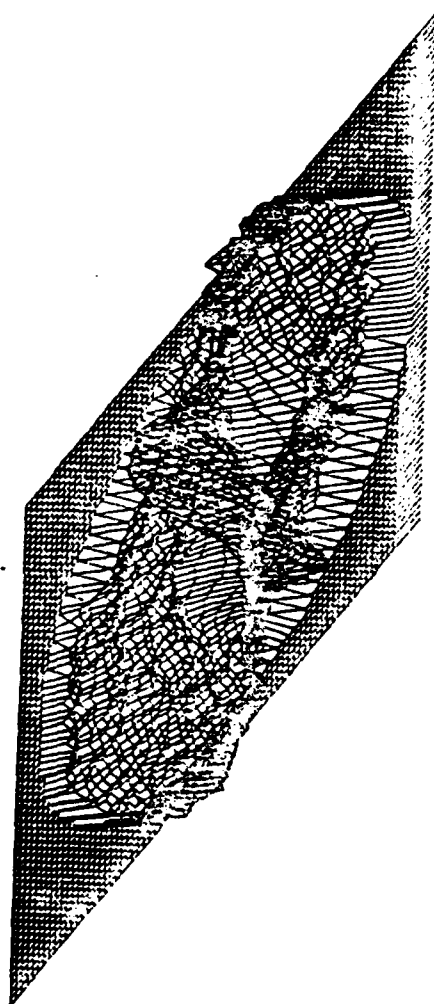


Figure A-8
Carpet Plot of Elevation Error for Case II

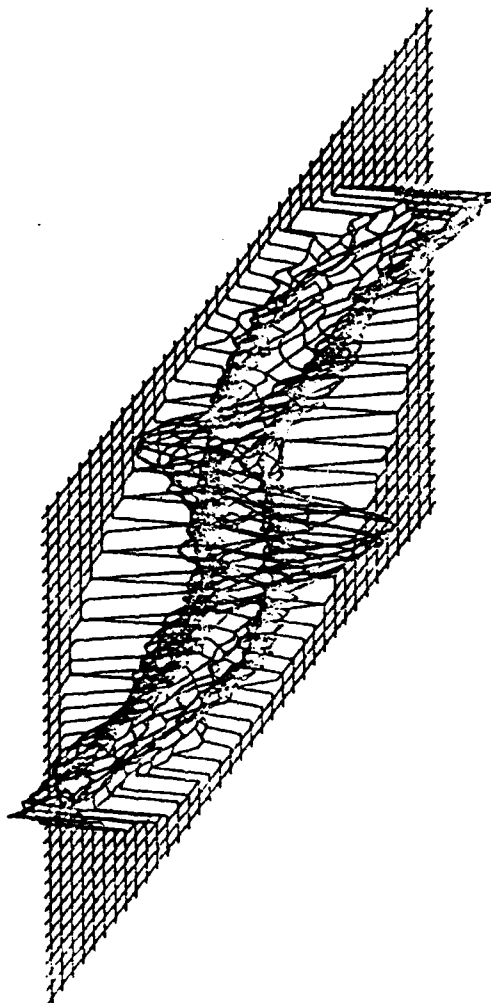


Figure A-9
Carpet II Plot of Azimuth Error for Case II

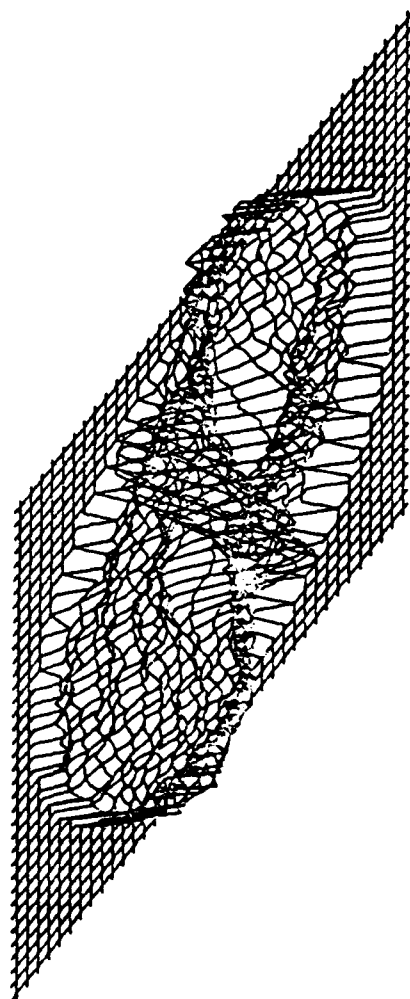


Figure A-10
Carpet II Plot of Elevation Error for Case II

Appendix B
Radome Positioner Software Listing

C FORTRAN SOURCE DRIVER FOR RMP-V2.1 TIM PALMER

C INITIALIZATION

```

COMMON      ISAMP
ISAMP      =23.0
1          PRINT 2
          PRINT 4
          PRINT 6
          PRINT 8
2          FORMAT (' THE UNIVERSITY OF ALABAMA IN HUNTSVILLE')
4          FORMAT (' RADOME MEASUREMENTS RECEIVER VERSION 2.1')
6          FORMAT ('          MODIFIED: 10/82')
8          FORMAT ('          BY: T PALMER')
          PRINT 10
          PRINT 12
          PRINT 14
10         FORMAT (' 1> ANTENNA SHOULD BE BORESIGHTED')
12         FORMAT (' 2> POSITIONER GIMBAL SPEEDS SHOULD BE SET')
14         FORMAT (' 3> POSITIONER SHOULD BE AT FIRST SAMPLE POINT')
15         PRINT 16
16         FORMAT (' 1=BORESIGHT ANTENNA,2=CONTINUE:')
          READ 18,IDUM
18         FORMAT ('
GO TO (50,20),IDUM
GO TO 15
20         PRINT 22
22         FORMAT (' ENTER SAMPLE SIZE (0.5-2.0):')
          READ 24,SAM
24         FORMAT ('
IF (SAM .LT. 0.5 .OR. SAM .GT. 2.0) GO TO 20
ISAMP=SAM+23.0
PRINT 245
245        FORMAT ('
26         FORMAT (' 1=GO,2=ABORT,E (ANY TIME)=ESCAPE:')
          CALL OPENIT
25         PRINT 28
          READ 28,IDUM
28         FORMAT ('
GO TO (30,32),IDUM
GO TO 25
30         PRINT 305
305        FORMAT (' TEST NOW ACTIVE.')
          CALL CNTRL
          PRINT 31
31         FORMAT (' END OF TEST:')
          GO TO 1
32         PRINT 34
34         FORMAT (' TEST ABORTED:')
          GO TO 1
50         PRINT 52
52         FORMAT (' REBOOT SYSTEM,TYPE <LOAD SIG>')
          END

```

	NAM	CNTL	
*	OPT	REL	
*	XREF	DSCT:TXBUF2,AZBIN,ELBIN,AZP,ELP,FIRSTP,TDAC,TDEL	
	XREF	PSCT:NETANL,RADLO,AIM,INIT,WPITER,CLOSIT	
	XDEF	CNTL	
*	CSCT		
*	ISAMP	RMB 2	
	DSCT		
ABSAC	RMB 2		
ABSEL	RMB 2		
AZCT	RMB 2		
ELCT	RMB 2		
LSAC	RMB 2		
LSEL	RMB 2		
*			
*	PSCT		
*			
CNTL	JSR	INIT	
	JSR	AIM	*GET ANGLES INTO AZBIN,ELBIN
TSTLP	LDA A	0FCF5H	*CHECK KEYBOARD FOR AN "E"
	CMP A	#45H	
	BNE	SMPL	
	JMP	TSTND	
SMPL	JSR	AIM	
	LDX	AZBIN	
	STX	ABSAC	
	LDX	ELBIN	
	STX	ABSEL	
TAZ	LDA A	AZBIN	
	AND A	#08	*CHECK FOR NEGATIVE ANGLE
	BEQ	PAZ	*GO IF POSITIVE
MAZ	LDA A	#00	
	LDA B	#00	*GET ABS VALUE OF AZ
	SUB A	AZBIN+1	
	SBC B	AZBIN	
	STA A	ABSAC+1	
	STA B	ABSEL	
PAZ	LDA A	ABSAC+1	
	LDA B	ABSEL	
	LDX	#0000	
	STX	TDAC	
	STX	AZCT	
	JSR	AZDLP	
	LDA A	ABSAC+1	
	LDA B	ABSEL	
	SUB A	TDAC+1	
	SBC B	TDAC	
	TST B		
	BNE	EXT	
	CMP A	#01	
	BGT	EXT	
	LDA A	AZBIN+1	
	LDA B	AZBIN	
	SUB A	LSAC+1	
	SBC B	LSAC	
	BMI	LSGTR	
	BPA	ACGTR	
LSGTR	LDA A	LSAC+1	

	LDA B	LSAZ
	SUB A	AZBIN+1
	SBC B	AZBIN
	CMP A	#03
	BGT	GSMP
	BRA	EXT
AZGTR	LDA A	AZBIN+1
	LDA B	AZBIN
	SUB A	LSAZ+1
	SBC B	LSAZ
	CMP A	#03
	BGT	GSMP
	BRA	EXT
EXT	JMP	TSTLP
GSMP	LDA	AZBIN
	STX	AZP
	STX	LSAZ
	LDA	ELBIN
	STX	ELP
	STX	LSEL
	JSR	NETANL
	JSP	RADLO
	LDA	#TMBUF2+2
	LDA B	#22
	JSP	WRITER
	JMP	TSTLP
TSTND	JSP	CLOSIT
	RTS	
AZDLP	SUB A	ISAMP+1
	SBC B	ISAMP
	BMI	DSAZ
	PSH A	
	PSH B	
	LDA A	AZCT+1
	LDA B	AZCT
	ADD A	#01
	ADC B	#00
	STA A	AZCT+1
	STA B	AZCT
	PUL B	
	PUL A	
	BRA	AZDLP
DSAZ	LDA A	AZCT+1
	LDA B	AZCT
	SUB A	#01
	SBC B	#00
	STA A	AZCT+1
	STA B	AZCT
	BMI	DON2
	PSH A	
	PSH B	
	LDA A	TDAC+1
	LDA B	TDAC
	ADD A	ISAMP+1
	ADC B	ISAMP
	STA A	TDAC+1
	STA B	TDAC
	PUL B	
	PUL A	
	BRA	DSAZ
DON2	RTS	
	END	

```

*
*
*      NAM      INIT
*
*      OPT      REL
*
*      XREF     ANY:CRB, DDRB, SRCR1, SRCR2
*      XDEF     INIT
*
*      PSCT
*
*      INIT
CLR      CRB      *INITIALIZE PIA
LDA A    #0FFH
STA A    DDRB
LDA B    #04H
STA B    CRB
STA A    DDRB
LDA A    #03H      *INITIALIZE ACIA'S
STA A    SRCR1
STA A    SRCR2
LDA A    #81H
STA A    SRCR1
LDA A    #01H
STA A    SRCR2
RTS
*
*
*      END
*

```

```

*      NAM      AIM
*
*      OPT      REL
*
*      XDEF      AIM
*
*      XREF      ANY:DATA,MUX,GAIN,CONVRT,STATUS
*
*      XREF      DECT:GAIN1,CHAN,AZBIN,ELBIN
*
**      SUBROUTINE TO READ THE AZ AND EL ANGLES FROM ANALOG PORTS
**      ANGLES ARE ON CHAN 3 FOR AZ AND 4 FOR EL
*
      PSCT
AIM      LDA A   GAIN1      *SET A/D GAIN
          STA A   GAIN
          CLR A   CHAN      *CLR CHAN POSITION
          LDA A   #03      *LOAD MUX TO 03 TO READ CHAN 3
          STA A   MUX
          LDA A   CHAN      *INITIALIZE CHAN TO 3
          ADD A   #3
BACK     STA A   CHAN
CKSTAT   STA A   CONVRT     *START CONVERSION PROCESS
          LDA A   STATUS     *WAIT UNTIL STATUS READY
          BPL CKSTAT
          LDA A   CHAN
          CMP A   #4        *CHAN 3 HAS BEEN READ READ CHAN 4
          BEQ CHAN4
          LDA DATA         *READ AND STORE AZ ANG
          STA AZBIN
          LDA A   CHAN      *INCREMENT CHAN TO 4
          ADD A   #1
          STA A   CHAN
          INC MUX          *INCREMENT MUX TO 03 TO READ CHAN 4
          BRA BACK         *BRANCH BACK TO READ CHAN 4 THE EL ANG
CHAN4    LDA DATA
          STA ELBIN
          RTS
          END

```

NAM NETANL

OPT REL

XREF ANY:GAIN,STATUS,DATA,CONVRT,MUX,DDFB
XREF DSCT:SAVEN,GAIN4,SWITCH,WHICH,FOUR,OFFSET,SWILOC,SWIPOS
XREF DSCT:CHAN,TIME,TWO,OUTLOC
XREF PSCT:COMPUT,WAIT
XDEF NETANL

PSCT

* "NETANL" SUBROUTINE
* CONTROLS SAMPLING OF SUM, AZINUTH, AND ELEVATION DATA. ALSO CONTROLS
* THE CONVERSION OF THIS DATA INTO DIGITAL FORM.
* EXIT: DIGITAL (TWO'S COMPLIMENT) DATA IS STORED IN THE ORDER IT
* WAS TAKEN UNDER THE FOLLOWING LABELS:
* AMPSUM, PHASUM, AMPAZ, PHAAZ, AMPEL, PHAEL

ETANL PSH A * SAVE ACC A
PSH B * SAVE ACC B
STX SAVEN * SAVE X REGISTER

LDA A GAIN4 *SET GAIN OF ADC AMP
STA A GAIN

CLR SWITCH * SET SWITCH MEMORY OUTPUT POINTER TO ZERO
CLR WHICH * SET SWITCH POSITION POINTER TO ZERO

EXT INC WHICH * INCREMENT SWITCH POSITION POINTER

LDA A WHICH * LOAD ACC A WITH SWITCH POSITION
CMP A FOUR * CHECK IF SWITCH POSITION IS STILL VALID
BEQ RESET * IF NOT, RESET SWITCH

STA A OFFSET * STORE OFFSET = WHICH TO COMPUTE NEW ADDRESS

LDX SWILOC * LOAD X REGISTER WITH ADDRESS TO BE CHANGED

JSR COMPUT * JUMP TO ROUTINE TO COMPUTE NEW ADDRESS

LDA A 0,X * LOAD THE CODE FROM THE COMPUTED ADDRESS IN ACC A

STA A DDFB * SEND THE CODE TO THE PIA TO SWITCH THE SWITCH

CLP CHAN * SET CHANNEL POINTER TO ZERO
CLR MUX * SET ACTUAL CHANNEL TO ZERO

LDX TIME * LOAD X REGISTER WITH TIME CONSTANT FOR WAIT ROUTINE
JSR WAIT * GO TO WAIT SUBROUTINE

BPA CHANNEL * ONLY DO FOLLOWING SECTION WHEN GETTING DATA

```

*
* CHANN2 INC NUX * INCREMENT ACTUAL CHANNEL
LDA A CHAN * LOAD ACC A WITH CURRENT CHANNEL POINTER
ADD A TWO * INCREMENT BY TWO
STA A CHAN * STORE NEW POINTER
*
* CHANN1 STA A CONVRT * START CONVERSION PROCESS BY WRITING INTO MEMORY
*
* CKSTAT LDA A STATUS * CHECK STATUS UNTIL READY
BPL CKSTAT * WHEN READY CONTINUE
*
*
* LDA A SWITCH * LOAD ACC A WITH SWITCH MEMORY POINTER
ADD A CHAN * ADD CHANNEL POINTER
STA A OFFSET * THIS IS THE OFFSET USED TO COMPUTE THE OUTPUT ADDRESS
*
* LDX OUTLOC * LOAD THE X REGISTER WITH THE ADDRESS TO BE CHANGED
*
* JSR COMPUT * JUMP TO THE ROUTINE TO COMPUTE THE NEW ADDRESS
*
*
* LDA A DATA * GET FIRST BYTE OF DATA
STA A 0,X * STORE IN PREDETERMINED POSITION
*
* INX * INCREMENT OUTPUT ADDRESS
*
* LDA A DATA+1 * GET SECOND BYTE OF DATA
STA A 0,X * STORE
*
* LDA A CHAN * CHECK IF ONLY CHANNEL 1 HAS BEEN DONE
BEQ CHANN2 * IF SO, GO DO CHANNEL 2
*
* LDA A SWITCH * LOAD ACC A WITH CURRENT SWITCH MEMORY POINTER
ADD A FOUR * INCREMENT BY FOUR
STA A SWITCH * STORE NEW POINTER
*
*
* BRA NEXT * REDO ROUTINE FOR NEXT SWITCH POSITION
*
*
* RESET LDA A SWIPDS * LOAD ACC A WITH CODE TO TURN SWITCH OFF
STA A DDRB * TURN SWITCH OFF
*
*
* LDX SAVEX * RESTORE X REGISTER
PUL B * RESTORE ACC B
PUL A * RESTORE ACC A
*
*
* RTS * RETURN TO CALLING ROUTINE
*
* END

```

```

*
*      NAM      COMPUT
*
*      OPT      REL
*
*
*      XDEF      COMPUT
*      XREF      DSCT:LOC,OFFSET,ZERO
*
*
*      PSCT
*
*
**      "COMPUT" SUBROUTINE
**      ADDS AN EIGHT BIT NUMBER (OFFSET) TO A SIXTEEN BIT NUMBER (ADDRESS)
**      ENTRY:      X REGISTER -- ADDRESS
**                  OFFSET -- OFFSET
**      EXIT:      X REGISTER -- MODIFIED ADDRESS
**      A AND B ACCUMULATORS ARE SAVED
*
*
COMPUT  STX      LOC      * TEMPORARILY STORE ADDRESS TO BE CHANGED
*
*      PSH A          * SAVE ACC A
*      PSH B          * SAVE ACC B
*
*      LDA A LOC      * LOAD ACC A WITH MS BYTE OF ADDRESS TO BE CHANGED
*      LDA B LOC+1    * LOAD ACC B WITH LS BYTE OF ADDRESS TO BE CHANGED
*
*      ADD B OFFSET   * ADD OFFSET TO LS BYTE
*      ADC A ZERO     * CARRY IF NECESSARY
*
*      STA A LOC      * TEMPORARILY STORE NEW ADDRESS
*      STA B LOC+1    *
*
*      LD%      LOC      * LOAD THE X REGISTER WITH THE NEW ADDRESS
*
*      PUL B          * RESTORE ACC B
*      PUL A          * RESTORE ACC A
*
*      RTS            * RETURN TO CALLING PROGRAM
*
*      END

```

```

*      NAM      WAIT
*
*      OPT      REL
*
*      XDEF     WAIT
*      PSCT
*
**      "WAIT" SUBROUTINE
**      STALLS (TIME) X (100 MICROSECONDS) WHERE TIME = CONTENTS OF X REGISTER
**      ACCUMULATORS A AND B ARE NOT AFFECTED
*
*      WAIT     PSH A          * SAVE CONTENTS OF ACC A
*
*      LDA A    #0BH          * LOAD ACC B WITH INITIAL COUNTDOWN
*
*      WAIT1    DEC A          * DECREMENT FOR COUNTDOWN
*      BNE      WAIT1         * REDO IF COUNTDOWN IS NOT FINISHED
*
*      LDA A    #0FH          * LOAD ACC A WITH SUBSEQUENT COUNTDOWN
*
*      DEX      WAIT1         * DECREMENT TIME
*      BNE      WAIT1         * USE MORE TIME IF TIME > 0
*
*      CMP A    0:X           * STALL FOR 5 MICROSECONDS
*
*      PUL A          * RESTORE CONTENTS OF ACC A
*
*      RTS          * RETURN TO CALLING ROUTINE
*
*      END

```

NAM RADLO

OPT REL

XREF DSCT:HEADER,FINAL
XREF DSCT:G1,BSEAZ,BSEEL,AZBIN,ELBIN
XREF DSCT:AMP3UM,PHASUM,AMPAZ,PHAAZ,AMPAL,PHAL
XREF DSCT:TXBUF2
XREF ANY:G1MSEP,G1LSEP,BAMSEP,BALSEP,BEMSEP,BELSEP
XREF ANY:ABMSEP,ABLSEP,EBMSEP,EBLSEP
XREF ANY:ASMSEP,ASLSEP,PSMSEP,PSLSEP
XREF ANY:ARMSEP,ARLSEP,PAMSEP,PALSEP
XREF ANY:REMSEP,RELSEP,PEMSEP,PELSEP
XREF ANY:DACA1,DACA2,DACA3,DACA4,DACA5
XDEF RADLO

PSCT

*
* "RADLO" (1) LOADS THE RADOME MEASUREMENTS
* INTO THE BUFFER FOR THE RFSS INTERFACE
* (2) LOADS THE DAC'S

ADLO LDX HEADER *LOAD HEADER AT TOP OF BUFFER
STX TXBUF2
LDX FINAL *LOAD FINAL AT BOTTOM OF BUFFER
STX TXBUF2+24
LDX #TXBUF2 *LOAD BUFFER STARTING ADDRESS INTO X

LDA A G1 *LOAD BUFFER ACCORDING TO
PREDETERMINED BYTE POSITIONS
LDA B G1+1
STA A 2,X
STA B 3,X
LDA A BSEAZ
LDA B BSEAZ+1
STA A 4,X
STA B 5,X
LDA A BSEEL
LDA B BSEEL+1
STA A 6,X
STA B 7,X
LDA A AZBIN
LDA B AZBIN+1
STA A 8,X
STA B 9,X
LDA A ELBIN
LDA B ELBIN+1
STA A 10,X


```

STA B 11,X
LDA A AMPSUM
LDA B AMPSUM+1
STA A 12,X
STA B 13,X
LDA A PHASUM
LDA B PHASUM+1
STA A 14,X
STA B 15,X
LDA A AMPAZ
LDA B AMPAZ+1
STA A 16,X
STA B 17,X
LDA A PHAAZ
LDA B PHAAZ+1
STA A 18,X
STA B 19,X
LDA A AMPEL
LDA B AMPEL+1
STA A 20,X
STA B 21,X
LDA A PHAEL
LDA B PHAEL+1
STA A 22,X
STA B 23,X

```

```

*
*
*

```

```

LDX G1
STX DACA1
LDX ASEA2
STX DACA2
LDX AZBIN
STX DACA3
LDX BSEEL
STX DACA4
LDX ELBIN
STX DACA5

```

```

*
*
*

```

```

RTS
END

```

```

      NAM      SDATA
      OPT      REL

XDEF  DEGRAD, TEN, TWENTY, CON1, CON2, CTS, THRX2, FIRSTP
XDEF  AZP, ELP, ICALPT, DEG, PANEL, MANEL, PANAZ, MANAZ
XDEF  G1, BSEAZ, BSEEL, REFSUM, SUMDB, ACDB, ELDB, GO, REL, PAZ
XDEF  DACR1, DACR2, DACR3, DACR4, DACR5, GOMSBP, GOLSBP
XDEF  KAMSBP, KALSBP, KEMSBP, KLSBP, SDMSBP, SLSBP, ADMCBP, ADLSBP
XDEF  EDMSBP, EDLSBP, GIMSBP, GILSBP, BAMSBP, BALSBP, BEMSBP, BELSBP
XDEF  ABP, EBP, TEMPX1
XDEF  REMSBP, RELSBP, SEMSBP, EELSBP
XDEF  REMSBP, RELSBP, GIMSBP, PLSBP
XDEF  RAMSBP, RALSBP, PAMSBP, PALSBP
XDEF  REMSBP, RELSBP, PEMSBP, PELSBP
XDEF  SF1A, SF1P, SFG1, SFBE
XDEF  TDZ2, TDEL, HEADER, FINAL
XDEF  THPSIN

      DSCT

DEGRAD  FDB  788EH      *DEGREES TO RADIAN'S CONVERSION FACTOR (.0174)
      FDB  0FA35H
TEN      FDB  10        *THE NUMBER TEN (10)
TWENTY  FDB  20        *THE NUMBER TWENTY (20)
CON1     FDB  00180H    * (.05)
      FDB  00000H
CON2     FDB  058EH      *DEGREES TO MILLI-RADIANS CONVERSION FACTOR (.174)
      FDB  0A057H
CTS      RMB  1
TEMPX1   FMB  2
THRX2    FMB  2
DEG      FDB  00073H    *DATA POINT 7: DEGREES OF MAXIMUM EL AND AZ
GO        FMB  4
REL      FDB  00180H
      FDB  00000H
KAZ      FDB  00180H
      FDB  00000H
PANEL    FDB  05A0H      *ERROR VOLTAGE AT +DEG ELEVATION
      FDB  0000H
MANEL    FDB  05A0H      *ERROR VOLTAGE AT -DEG ELEVATION
      FDB  0000H
PANAZ    FDB  05A0H      *ERROR VOLTAGE AT +DEG AZIMUTH
      FDB  0000H
MANAZ    FDB  04A0H      *ERROR VOLTAGE AT -DEG AZIMUTH
      FDB  0000H
G1        RMB  2        *TRANSMISSION LOSS, PHOTONIC LOOING AT ANGLE
BSEAZ    RMB  2        *BORESIGHT ERROR AT ANGLE (AZIMUTH)
BSEEL    RMB  2        *BORESIGHT ERROR AT ANGLE (ELEVATION)
REFSUM   FDB  04A0H
      FDB  0000H
SUMDB    RMB  4
ACDB     RMB  4
ELDB     RMB  4
FIRSTP   RMB  1
AZP      RMB  2
ELP      RMB  2
TDZ2     RMB  2
TDEL     RMB  2
ICALPT   RMB  1
ABP      FCB  5
EBP      FCB  6
HEADER   FDB  0FFFFH

```

```

FINAL      FDB      0FF0DH
GOMSEP     FCB      1
GOLSEP     FCB      2
KAMSEP     FCB      3
KALSEP     FCB      4
KEMSEP     FCB      5
KELSEP     FCB      7
SDMSEP     FCB      1
SDLSEP     FCB      2
ADMSEP     FCB      3
ADLSEP     FCB      4
EDMSEP     FCB      6
EDLSEP     FCB      7
GIMSEP     FCB      2
GILSEP     FCB      3
BAMSEP     FCB      4
BALSEP     FCB      5
BEMSEP     FCB      6
BELSEP     FCB      7
ABMSEP     FCB      8
ABLSEP     FCB      9
EBMSEP     FCB     10
EBLSEP     FCB     11
ASMSEP     FCB     12
ASLSEP     FCB     13
PSMSEP     FCB     14
PSLSEP     FCB     15
ARMSEP     FCB     16
ARLSEP     FCB     17
PRMSEP     FCB     18
PALSEP     FCB     19
REMSEP     FCB     20
RELSEP     FCB     21
PEMSEP     FCB     22
PELSEP     FCB     23
*
*
SFIA       FDB      006A3H
           FDB      0038FH
SFIP       FDB      00483H
           FDB      0030CH
SFGI       FDB      00788H
           FDB      04000H
SFBE       FDB      00BFFH
           FDB      0E000H
TMPSIN     RMB      4
*
*      ASCT
*
**      DAC LOCATIONS
*
DACR1      EOU      0E03EH
DACR2      EOU      0E03CH
DACR3      EOU      0E03BH
DACR4      EOU      0E03EH
DACR5      EOU      0E03AH
*
*
*      END
*

```

```

*
*      NAM      RDATA
*
*      OPT      REL
*
*
XDEF  TEMPA,TEMPB,TEMPX,BCDSGN,BINUPR,OUTBUF
XDEF  AZBCDS,AZBCD,ELBCDS,ELBCD,AZBIN,ELBIN,IMPBCD
XDEF  IMPBUF,RXBUF1,TXBUF1,TXBUF2,RXBUIP,TXBUIP
XDEF  AZANG,ELANG,PLUS,APST,DCML,CP,AINTP,TXDRE
XDEF  SRCR1,RTDR1,SRCP2,RTDR2
XDEF  APUDAT,AFUSTA,DDPA1
*
*
      DSCT
PLUS   FCB    2BH
APST   FCB    27H
DCML   FCB    2EH
CR     FCB    0DH
TXDRE  FCB    02H
*
*
**      ALLOCATED MEMORY AREA.
*
**      TEMPORARY MEMORY VARIABLES.
*
TEMPA   RMB    1           *ACCUMULATOR A (BCDBIN,BINANG).
TEMPB   RMB    1           *ACCUMULATOR B (BINANG).
TEMPX   RMB    2           *INDEX REGISTER (MOVEBUF,BCDANG).
BCDSGN  RMB    1           *ASCII SIGN OF BCD ANGLE (BINANG,BCDANG,ANGLE).
BINUPR  RMB    1           *USED IN FINDING MS BYTE OF BINARY VALUE (BCDBIN).
OUTBUF  RMB    2           *POINTER TO TEMPORARY OUTPUT BUFFER (MOVEBUF).
*
      DSCT
*
*
**      DEDICATED MEMORY VARIABLES.
*
AZBCDS  RMB    1           *ASCII SIGN OF ELEVATION BCD ANGLE (ANGLE).
AZBCD   RMB    2           *PACKED BCD FORM OF AZIMUTH ANGLE (ANGLE).
ELBCDS  RMB    1           *ASCII SIGN OF ELEVATION BCD ANGLE (ANGLE).
ELBCD   RMB    2           *PACKED BCD FORM OF ELEVATION ANGLE (ANGLE).
AZBIN   RMB    2           *TWO'S COMPLIMENT OF AZIMUTH ANGLE (ANGLE).
ELBIN   RMB    2           *TWO'S COMPLIMENT OF ELEVATION ANGLE (ANGLE).
IMPBCD  RMB    1           *USED IN PACKING BCD ANGLE (BCDPCK).
RXBUIP  RMB    2           *POINTER FOR ASCII CHAR IN PCVR BUFFER 1 (RCVFRF).
TXBUIP  RMB    2           *POINTER FOR ASCII CHAR IN TXMT BUFFER 2 (TXMTAI).
*
*
*
**      EXTERNAL INTERFACE BUFFER AREA
*
*

```

```

TXBUF  RMB 20      *TEMPORARY BUFFER AREA (BCDANG)
ACANG  EQU TXBUF   *LOCATION IN RXBUF OF ACIMUTH BCD ANGLE (ANGLE)
ELANG  EQU TXBUF+10 *LOCATION IN RXBUF OF ELEVATION BCD ANGLE (ANGLE)
RXBUF1 FDB 0000H   *ASCII CHARS REC'D FROM POSITIONER (BCDANG,RCVPRP)
        FDB 0000H
        FDB 0000H
        FDB 002EH
        FDB 0027H
        FDB 0000H
        FDB 0000H
        FDB 0000H
        FDB 002EH
        FDB 0027H
TXBUF1  RMB 20
TXBUF2  RMB 26
*
*
*      ASCT
*
**     I/O DEVICE EQUATE SYMBOLS
*
*
SPCR1  EQU 0E004H
RTDR1  EQU 0E005H
SRCR2  EQU 0E008H
RTDR2  EQU 0E009H
*
**     APU DATA
*
APUDAT EQU 0E00CH
APUSTA EQU 0E00DH
DDRA1  EQU 0E00EH
AINTP  EQU 0FFFFH
*
*      END

```

```

*
*      NAM      DDATA
*
*      OPT      REL
*
*      XDEF      SAVEK,LOC,SWITCH,WHICH,CHAN,OFFSET
*      XDEF      SWILOC,SWIPOS,CRA
*      XDEF      OUTLOC,AMPSON,PHASUM,AMPAC,PHAC,AMPCL,CHREL
*      XDEF      DDFB,CRB,BASE,GAIN,MUX,CONVRT,STATUS,DATA
*      XDEF      GAIN1,GAIN2,GAIN4,GAIN5
*      XDEF      TIME,ZERO,TWO,FOUR
*
*
*      DSCT
GAIN1      FCB      00H
GAIN2      FCB      01H
GAIN4      FCB      02H
GAIN5      FCB      03H
TIME       FCB      0003H
ZERO       FCB      00H
TWO        FCB      02H
FOUR       FCB      04H
*
*
**      ALLOCATED MEMORY AREA
*
**      TEMPORARY MEMORY VARIABLES
*
SAVEK      RMB      2      * USED TO SAVE CONTENTS OF X REGISTER
LOC        RMB      2      * USED WHEN COMPUTING ADDRESS PLUS OFFSET
SWITCH     RMB      1      * USED IN INCREMENTING PAGE DEF MEMORY POSITION
                        (SOFTWARE SWITCH)
WHICH      RMB      1      * POINTER USED TO KEEP TRACK OF SWITCH POSITION
CHAN       RMB      1      * POINTER USED TO KEEP TRACK OF CHANNEL SELECTION
OFFSET     RMB      1      * COMPUTED OFFSET USED WHEN COMPUTING NEW ADDRESS
*
**      DEDICATED MEMORY VARIABLES

```

```

*
SWILOC FDB SWIP0S * LOCATION OF SWITCH POSITION CODES
SWIP0S FCB 0FFH * SWITCH POSITION -- OFF
FCB 0FEH * SWITCH POSITION -- ONE
FCB 0FDH * SWITCH POSITION -- TWO
FCB 0FBH * SWITCH POSITION -- THREE
FCB 0F7H * SWITCH POSITION -- FOUR

*
** EXTERNAL INTERFACE BUFFER AREA
*
OUTLOC FDB AMPSUM * LOCATION OF MEMORY RESERVED FOR OUTPUT
AMPSUM FDB 0001H * SUM AMPLITUDE
PHASUM FDB 0001H * SUM PHASE
AMP02 FDB 0001H * AZIMUTH AMPLITUDE
PH02 FDB 0001H * AZIMUTH PHASE
AMP0L FDB 0001H * ELEVATION AMPLITUDE
PH0L FDB 0001H * ELEVATION PHASE
*
** EXTERNAL INTERFACE BUFFER AREA
*
CRA RMB 2 *TERMINATES CONTROL BASED ON AN "S"
ASCT
DDPB EQU 0E002H * DATA DIRECTION REGISTER PIA PORT B
* (SWITCH CONTROL)
CRB EQU 0E003H * CONTROL REGISTER PIA PORT B
BASE EQU 0E040H * BEGINNING OF ADC BOARD " MEMORY " LOCATIONS
GAIN EQU BASE+9H * MEMORY LOCATION TO ACCESS GAIN
MUX EQU BASE+0AH * MEMORY LOCATION TO ACCESS MULTIPLEXER CHANNEL SELECT
CONVRT EQU BASE+0EH * MEMORY LOCATION TO ACCESS CONVERT COMMAND
STATUS EQU BASE+0CH * MEMORY LOCATION TO ACCESS STATUS
DATA EQU BASE+0DH * MEMORY LOCATION TO ACCESS ADC DATA MS BYTE
*
END

```

NO UNDEFINED SYMBOLS

MEMORY MAP

S	SIZE	STR	END	COMM
B	0000	0040	0040	0000
C	0002	2000	2001	0002
D	035E	2002	235F	0002
P	1B57	2360	3EB6	000F

MODULE NAME	BSCT	DSCT	PSCT
MAIN	0040	2002	2360
CNTL	0040	2060	274E
INIT	0040	2078	2850
AIM	0040	2078	2874
NETAHL	0040	2078	28B4
RADLO	0040	2078	2936
COMPUT	0040	2078	29D2
WAIT	0040	2078	29F0
SDATA	0040	2078	2A00
RDATA	0040	2108	2A00
BDATA	0040	217A	2A00
	0040	21A2	2A00
FTNRUN	0040	2256	2C38

COMMON SECTIONS

NAME	S	SIZE	STR
.ADDR	P	000F	3EA8
.ADRDC	D	0002	235E

DEFINED SYMBOLS

MODULE NAME: MAIN
MAIN P 2360

MODULE NAME: CNTL
CNTL P 274E

MODULE NAME: INIT
INIT P 2850

MODULE NAME: AIM
AIM P 2874

MODULE NAME: NETAHL
NETAHL P 28B4

MODULE NAME: RADLO
RADLO P 2936

MODULE NAME: COMPUT
COMPUT P 29D2

MODULE NAME: WAIT
WAIT P 29F0

MODULE NAME: SDATA

AALSEP	D	20E0	AAMSEP	D	20E8	AELSEP	D	20E4	AMSEP	D	20E3
ABP	D	20C8	ADLSEP	D	20DA	ADMSEP	D	20D4	RELSEP	D	20F3
AMSEP	D	20EF	ASLSEP	D	20E3	ASMSEP	D	20E7	AZDB	D	20E9
AZP	D	20C2	SALSEP	D	20E0	BAMSEP	D	20DF	BELSEP	D	20E2
BEMSEP	D	20E1	BSEAZ	D	20AD	BSEEL	D	20AF	CON1	D	2080
CON2	D	2084	CTS	D	2088	DACA1	A	E03E	DACA2	A	E03C
DACA3	A	E028	DACA4	A	E03E	DACA5	A	E03A	DEG	D	208D
DEGRAD	D	2078	EBLSEP	D	20E6	EBMSEP	D	20E5	EBP	D	20CC
EDLSEP	D	20DC	EDMSEP	D	20D8	ELDB	D	208D	ELP	D	20C4
FINAL	D	20CF	FIRSTP	D	20C1	G0	D	208F	GOLSEP	D	20D2
GOMSEP	D	20D1	G1	D	20AB	GILSEP	D	20DE	GIMSEP	D	20D0
HEADER	D	20CD	ICALPT	D	20CA	KALSEP	D	20D4	KAMSEP	D	20D3
KAZ	D	2097	KEL	D	2093	KELSEP	D	20D6	KEMSEP	D	20D5
MANAZ	D	20A7	HANEL	D	209F	PALSEP	D	20EE	PAMSEP	D	20ED
PANAZ	D	20A3	PANEL	D	209B	PELSEP	D	20F2	PAMSEP	D	20F1
PSLSEP	D	20EA	PSMSEP	D	20E9	REFSUM	D	20B1	SDLSEP	D	20D8
SDMSEP	D	20D7	SFBE	D	20FF	SFG1	D	20FB	SF1A	D	20F3
SFIP	D	20F7	SUMDB	D	20B5	TDAZ	D	20C5	TDEL	D	20C3
TEMPX1	D	2089	TEN	D	207C	TMPSIN	D	2103	TMPX2	D	208E
TWENTY	D	207E									

MODULE NAME: PDATA

AINTP	A	FFF8	APST	D	2109	APUDAT	A	E00C	APUSTA	A	E00D
AZANG	D	2124	AZBCD	D	2116	AZBCDS	D	2115	AZBIN	D	2118
BCDSGN	D	2111	BINUPR	D	2112	CR	D	2108	DCML	D	210A
DDRA1	A	E000	ELANG	D	212E	ELBCD	D	2119	ELBCDS	D	2113
ELBIN	D	211D	OUTBUF	D	2113	PLUS	D	2108	RTDR1	A	E005
RTDR2	A	E009	RXBUF1P	D	2120	RXBUF1	D	2138	SRCP1	A	E004
SRCP2	A	E003	TEMPA	D	210D	TEMPB	D	210E	TEMPX	D	210F
TMPBCD	D	211F	TMPEUF	D	2124	TABU2P	D	2122	TXBUF1	D	214C
TXBUF2	D	2160	TXDRE	D	210C						

MODULE NAME: DDATA

AMPAC	D	2198	AMPCL	D	219C	AMPSUM	D	2194	BASE	A	E040
CHAN	D	2189	CONVRT	A	E04B	CRA	D	21A0	CRB	A	E003
DATA	A	E04D	DDPB	A	E002	FOUR	D	2182	GAIN	A	E049
GAIN1	D	217A	GAIN2	D	217B	GAIN4	D	217C	GAINS	D	217D
LOC	D	2185	MUX	A	E04A	OFFSET	D	218A	OUTLOC	D	2192
PHARZ	D	219A	PHREL	D	219E	PHASUM	D	2196	SAVEH	D	2183
STATUS	A	E04C	SWILOC	D	213B	SWIPOS	D	218D	SWITCH	D	2187
TIME	D	217E	TWO	D	2181	WHICH	D	2188	ZERO	D	2180

MODULE NAME:

CLOSIT	P	2C00	OPENIT	P	2AA8	WRITER	P	2BD6
--------	---	------	--------	---	------	--------	---	------

MODULE NAME: FTHFUN

BUF#	D	32B7	COMBA	P	3E4F	EBUF#	D	333C	FILE#	D	31B4
LPUSE#	D	32B7	RUN#	P	3C38	X1#	D	3289	XDFIN#	P	35C9
XDKOT#	P	35CC	XPUIND#	P	35CF						

RLOAD
BASE
IDON
LOAD=LIB
LIB=FORLB
MO=MAP1.MO
MAPF
MO=MCN
MAPF
OBJA=OBJ1.LO
LOAD=LIB
LIB=FORLB
EXIT

TPCNT.CF

MERGE FSTP.RD,TPCNT.RD,INIT.PD:1,AIN.PD:1,COMPUT.RD:1,TODISK.RD:1,LIE.PD
MERGE LIB.RD,NETANL.PD:1,RADLO.PD:1,WAIT.PD:1,DATA.RD:1,LIE.RD

Appendix C
Radome Measurements Receiver System Software Listing


```

      JMP      ST28A
ST28C LDA A    ELKEY
      LDA B    ELKEY+1
      LDX      #PROGB
      NOP
      STA A    ELKEY
      STA B    ELKEY+1
      TST      CARRY
      BEQ      ST28C1
      LDA A    #2DH
      STA A    ELKEYS
ST28C1 LDX      #ST28C2
      STX      STADDR
      NOP
ST28C2 JSR      NEWAZ
      LDA A    AZSIGN
      STA A    AZKEYS
      LDX      #ST28C3
      STX      STADDR
      NOP
ST28C3 LDA A    AZSIGN      ;CURR AZ SIGN
      CMP A    #2BH        ; "+"
      BEQ      ST28C4
      LDA A    #2BH
      STA A    AZKEYS
      BRA      ST28C5
ST28C4 LDA A    #2DH
      STA A    AZKEYS
ST28C5 LDX      #ST28A
      STX      STADDR
      JMP      ST28A

```

```

; "NEWAZ" SUBROUTINE THAT CALCULATES AZ POSITION BASED ON EL AND PROGA
NEWAZ

```

```

      LDA A    ELKEY      ;GET ELEVATION MSB
      JSR      BCDBIN     ;GET BINARY EQUIV
      LDA A    TEMPA      ;BINARY EQUIV
      ADD A    TEMPA      ;BINARY EQUIV
      STA A    SAVEA      ;SAVE THIS ONE
      LDX      #TAB1      ;AZ TABLE POINTER
      STX      SAVEX1     ;SAVE POINTER
      LDA A    SAVEX1+1
      LDA B    SAVEX1
      ADD A    SAVEA      ;GET NEW ADDRESS
      ADC B    #00H
      STA A    SAVEX1+1   ;SAVE IT
      STA B    SAVEX1
      LDX      SAVEX1
      LDA A    0,X        ;GET AZIMUTH
      LDA B    1,X        ;GET AZIMUTH LSB
      STA A    AZKEY      ;STORE INTO AZKEY
      STA B    AZKEY+1    ;SAME FOR LSB
      RTS               ;DONE

```

```

TAB1
WORD 03200H
WORD 03198H
WORD 03194H
WORD 03186H
WORD 03175H
WORD 03161H
WORD 03143H
WORD 03122H
WORD 03100H
WORD 03070H
WORD 03040H
WORD 03005H
WORD 02966H
WORD 02924H

```

	WORD	02877H	
	WORD	02826H	
	WORD	02771H	
	WORD	02711H	
	WORD	02646H	
	WORD	02575H	
	WORD	02500H	
	WORD	02414H	
	WORD	02324H	
	WORD	02225H	
	WORD	02117H	
	WORD	02000H	
	WORD	01865H	
	WORD	01717H	
	WORD	01549H	
	WORD	01353H	
	WORD	01113H	
	WORD	00794H	
	WORD	00000H	
BCDBIN	CLR	TEMPA	
	PSH A		;SAVE A
	AND A	#0F0H	;GET UPPER 4 BITS
	LSR A		;MOVE 1 BIT RIGHT
	LSR A		;THAT MAKES 2
	LSR A		;THERES 3
	LSR A		;THAT'S ALL FOLKS
	CLC		;CLEAR ANY CARRY
TNLP	TST A		
	BEO	ONELP	
	CLR	TEMPA	
	PSH A		;SAVE SHIFTED A (STACK: SHA,A)
LP1	LDA A	TEMPA	
	ADD A	#0AH	;ADD 10
	STA A	TEMPA	
	PUL A		;GET SHIFTED A BACK
	DEC A		;DEC COUNTER
	BEO	ONELP	;IF FINISHED
	PSH A		;SAVE SHIFTED A AGAIN
	BRA	LP1	;DO IT AGAIN
ONELP	PUL A		;FULLS ORIGINAL A
	AND A	#0FH	;GET LS NIBBLE
	TST A		;SEE IF DONE
	BEQ	EBBC	;GO IF NO ONES
	PSH A		
LP2	LDA A	TEMPA	;GET INTERMEDIATE RESULT
	ADD A	#01H	;INCREMENT BY ONE
	STA A	TEMPA	;SAVE RESULT
	PUL A		;GET ONE COUNTER
	DEC A		;DECREMENT
	BEO	EBBC	;GO IF DONE
	PSH A		;NOT DONE YET
	BRA	LP2	
EBBC	RTS		
	END		

	SECTION	BLK, ABSOLUTE
	ORG	0000H
DISBUF	BLOCK	20
SIBUF	BLOCK	21
TEMPX	BLOCK	2
RAL IUS	BLOCK	2
FPTJ2	BLOCK	4
ELRESULT	BLOCK	5
AZRESULT	BLOCK	5
INTREG	BLOCK	2
ENTRY1	BLOCK	1
ENTRY2	BLOCK	1
SAVEB	BLOCK	1
SAVEC	BLOCK	1
CHARBF	BLOCK	1
CHARPT	BLOCK	2
CHARCT	BLOCK	2
CHNUM	BLOCK	1
SAVEA	BLOCK	1
SAVEX	BLOCK	2
SAVEX1	BLOCK	2
TEMPA	BLOCK	1
TEMPB	BLOCK	1
MSFENC	BLOCK	1
LSBENC	BLOCK	1
LETA	BLOCK	1
LETB	BLOCK	1
BCDA	BLOCK	1
BCDB	BLOCK	1
SAVDEC	BLOCK	1
ANGLE	BLOCK	3
SIGN	BLOCK	1
AZSIGN	BLOCK	1
ELSIGN	BLOCK	1
AZBCD	BLOCK	2
ELBCD	BLOCK	2
TEMPX1	BLOCK	2
TEMPX2	BLOCK	2
ENTRYA	BLOCK	1
ENTRYB	BLOCK	1
FEVENT	BLOCK	1
TEMPA1	BLOCK	1
TEMPB1	BLOCK	1
FEYC	BLOCK	1
AZKEY	BLOCK	2
ELKEY	BLOCK	2
AZKEYS	BLOCK	1
ELKEYS	BLOCK	1
MFLAG	BLOCK	1
PFLAG	BLOCK	1
MINUEN	BLOCK	1
SPEEDA	BLOCK	1
SPEEDE	BLOCK	1
AZMAG	BLOCK	2
ELMAG	BLOCK	2
AZEL	BLOCK	1
TEMPS	BLOCK	1
PROGN	BLOCK	1
PROGL	BLOCK	1
PROGA	BLOCK	2
PROGB	BLOCK	2
PROGC	BLOCK	2
PFLAG	BLOCK	1
DPLAGA	BLOCK	1
DPLAGE	BLOCK	1
SFLAGA	BLOCK	1

```

SFLAGE BLOCK 1
TEMPD BLOCK 2
BCDVSR BLOCK 2
FPTL BLOCK 2
FPTAZ BLOCK 2
FPTLS BLOCK 1
FPTAZS BLOCK 1
PROCNT BLOCK 1
STADDR BLOCK 2
PROANG BLOCK 2
BINANG BLOCK 2
SINE BLOCK 2
COSINE BLOCK 2
SSIGN BLOCK 1
CSIGN BLOCK 1
SAVE1 BLOCK 1
BINUPR BLOCK 1
FELLIM BLOCK 2
NELLIM BLOCK 2
PAZLIM BLOCK 2
NAZLIM BLOCK 2
LFLAGE BLOCK 1
LFLAGA BLOCK 1
MSGFLG BLOCK 1
SAVEX2 BLOCK 2

```

MODIFICATION V1.3

```

;
SPEED BLOCK 1
GIMSPEED BLOCK 1
AZSPEED BLOCK 1
ELSPEED BLOCK 1
AZSPD BLOCK 1
ELSPD BLOCK 1
;
CARRY BLOCK 1
;
;

```

;I/O EQUATES

```

HAFSPD EQU 0E0H
QUASPD EQU 0E7H
DDRA2 EQU 0B404H ;MS 4 BITS OF DAC #1-AZIMUTH
CRA2 EQU 0B405H
DDRB2 EQU 0B406H ;LS 8 BITS OF DAC #1-AZIMUTH
CRB2 EQU 0B407H
DDRA3 EQU 0B800H ;LS 4 BITS OF DAC #2-ELEVATION
CRA3 EQU 0B801H
DDRB3 EQU 0B802H ;MS 8 BITS OF DAC #2-ELEVATION
CRB3 EQU 0B803H
DISAZ EQU 0C00H
DISEL EQU 0C0AH
MSBSEL EQU 0B003H
LSBSEL EQU 0B00CH
MSBSAZ EQU 0B001H
LSBSAZ EQU 0B000H
DDRA EQU 0B400H
CRA EQU 0B401H
DDRB EQU 0B402H
CRB EQU 0B403H
ACIAS EQU 0B40BH ;ACIA STAU/CONTROL REGISTER
ACIAD EQU 0B409H ;ACIA DATA REGISTER
APUDATA EQU 0B804H ;APU DATA INPUT/OUTPUT
APUSTAT EQU 0B805H ;APU COMMAND INPUT AND STATUS OUTPUT
ETHSPD EQU 0F0H ;(MOD 1.3)

```

```

;
;
; MAIN PROGRAM- 2000-3016 HEX
;

```



```

;
;
SECTION      MAIN
ORG          2000H

;
; INITIALIZE PIAS
;
GOE          LDS      #0FFFH
             NOP
             SEI
             LDA A    #3          ;00000011= MASTER RESET
             STA A    ACIAS       ;RESET ACIA
             LDA A    #81H       ;10000001 = 7 BITS, EVEN PARITY, 2 STOP BITS
             STA A    ACIAS       ;SET ACIA FOR RECEIVER INT, TXMIT INT OFF
             CLR      CRA        ;CLEARS CONTROL REG A
             CLR      CRB        ;CLEARS CONTROL REG B
             CLR      CRA2
             CLR      CRB2

;
; ADDITION TO INIT ROUTINE
; COMPENSATION FOR INVERTED BUS DRIVERS
; (MOD 1.2)
;
             LDA A    #0FFH      ;GET OPPOSITE OF 00
             STA A    CRA2       ;CLEAR CONTROL REG OF A SIDE
             STA A    CRB3       ;CLEAR CONTROL REG OF B SIDE
             CLR      DDRB3      ;SETS UP B SIDE OF DATA PORT A ALL OUTPUTS
             LDX      #8400H
             LDA A    #0F0H
             STA A    0,X
             STA A    DDRA3      ; (MOD 1.2) COMPENSATION FOR INV BUS DRIVERS
             LDA A    #7
             STA A    1,X
             LDA A    #0FH
             STA A    0,X
             STA A    4,X
             LDA A    #0FFH
             STA A    2,X
             STA A    6,X
             LDA A    #004H
             STA A    CRA2
             STA A    CRB2
             LDA A    #0FBH      ; (MOD 1.2) PUTS 04 INTO CONTROL REGISTER
             STA A    CRA3
             STA A    CRB3
             LDA A    #00DH
             STA A    CRB        ;SELECTS OUTPUT REGISTER B

;
;   INITIALIZED MOTORS TO ZERO SPEED, ETC.
;
             LDX      #TEMPX
NEXTC        CLR      0,X        ;CLEARS LOCATION POINTED TO BY THE X REGISTER
             INX
             CFX      #CARRY+1
             BNE      NEXTC

;
; ADDITION TO THE INITIALIZATION ROUTINE
; INITIALIZE ASCII FORM OF GIMBAL SPEEDS TO FULL SPEED.
; (MOD 1.3)
;
             LDA A    #39H      ;ASCII "9"
             STA A    AISPEED    ;AZ GIMBAL AT FULL SPEED
             STA A    ELSPEED    ;ELEVATION GIMBAL AT FULL SPEED

;
             LDX      #3500H
             STX      PELLIM

```

```

SIX      HELLIM
STX      FAZLIM
STX      NAZLIM
LDA A    #0DH      ;INITIALIZE (CR) IN SIBUF
STA A    SIBUF+20
LDA A    #0FFH
STA A    LSBSSEL
LDA A    #0FFH
STA A    LSBSAZ
STA A    SFLAGA    ;SETS AZ SPEED FLAG TO NOTE ZERO SPEED
STA A    SFLAG     ;SETS EL " " " " " " "
LDA A    #001H
STA A    MSBSAZ    ;TURNS ON POWER TO AZ MOTOR
STA A    MSBSSEL   ;TURNS ON POWER TO EL MOTOR

;
;   INITIALIZES CONTROL LOOP SUCH THAT THE POSITIONER
;   WILL NOT MOVE UPON POWER-UP (MOD 1.1)
;

JSR      SHAENC    ;READ ANGLES
LDX      AZBCD
STX      AZKEY     ;UPDATES AZIMUTH KEYENTRY WITH
LDX      ELBCD     ;CURRENT AZIMUTH LOCATION
STX      ELKEY     ;SAME FOR ELEVATION
LDX      AZSIGN
STX      AZKEYS    ;CURRENT AZ SIGN STATUS

;
NOP      ;FIX FOR THE "CLI" INSTR THAT FOLLOWS
CLI

;::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::
;
;   BEGIN STATE TABLES
;
;::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::
;
MSGA     LDX      #MSG12
        JSR      ASCDIS    ;DISPLAY "THE GA. TECH RFSS"
        LDA B    #20
        JSR      WAITE     ;WAIT FOR 2 SECONDS
        LDX      #MSG13
        JSR      ASCDIS    ;DISP "RADOME POSITIONER"
        LDA B    #10
        JSR      WAITE     ;WAIT FOR 1 SECOND
        LDX      #MSG14
        JSR      ASCDIS    ;DISPLAY " VERSION 1.5 "
MSGB     LDA B    #10
        JSR      WAITE

;
;   STATE ZERO
;   MAIN CONTROL LOOP
;
STO      LDA A    IFLAG    ;IDLE STATE
        BFL      STOA
        CLR      IFLAG    ;CLEARS "KEY PRESSED" FLAG
        LDA A    KEYENT    ;GETS KEYCODE OF KEY PRESSED
        LDX      #SFO      ;PUTS 0 STATE POINTER IN INDEX REG
        JSR      ADDCAL    ;JUMPS TO ROUTINE TO CALC NEXT STATE
        LDX      0,X
        JMP      0,X

;
;   AZIMUTH MOTOR CONTROL LOOP
;
STOA     JSR      SHAENC    ;READS AZ AND EL ANGLES
        LDA A    MFLAG
        BMI      STO
        LDA A    AZKEYS
        CMP A    AZSIGN    ;SEE IF BOTH SIGNS EQUAL

```

```

      BEQ      STOX      ;BRANCH TO DO A BCDSUB IF SIGNS ARE SAME
      LDA A    AZKEY+1
      ADD A    AZBCD+1   ;FIND LS BYTE OF AZ MAGNITUDE DIFF
      DAA
      STA A    AZMAG+1
      LDA A    AZKEY
      ADC A    AZBCD      ;FIND MS BYTE OF AZ MAG DIFF
      DAA
      LDA B    AZMAG+1
      STA A    AZMAG      ;AZ MAG DIFF NOW IN A AND B REGS
      BRA      STOX2
      LDA A    AZKEY
      LDA B    AZKEY+1
      LDX      #AZBCD     ;PUT ADDRESS OF BCD CURRENT LOC IN INDEX REG
      JSR      BCDSUB     ;JUMPS TO ROUTINE TO SUBTR BCD #'S
      STA A    AZMAG
      STA B    AZMAG+1
      ;
      ; ADDITION TO TIGHTEN CONTROL LOOP (AZ) TO .1 DEGREE (MOD 1.1)
      ;
      STOX2    TST A      ;START <0.2 DEGREE TEST
      BNE      STOX1      ;BRANCHES TO <0.5 DEG TEST IF BCD WORD NOT <0.2
      CMP B    #15H       ;COMPARING T 0.15 DEG
      BHI      STOX1      ;BRANCHES TO <0.5 DEG TEST IF BCD WORD NOT <0.2
      LDA A    #0FFH      ;CURRENT POSITION IS LESS THAN 0.2 DEG
      STA A    SFLAGA     ;SETS AZ SPEED FLAG WITH CORRECT SPEED
      STA A    LSBSAZ     ;STOP AZ MOTOR WITH ZERO SPEED
      BRA      STOE
      STOX1    TST A      ;START <0.5 DEG TST
      BNE      STOB       ;BRANCHES IF <0.5 DEG TEST IF BCD WORD NOT <0.5
      CMP B    #050H
      BHI      STOB       ;BRANCHES IF <0.5 DEG TEST IF BCD WORD NOT <0.5
      LDA A    #ETHSPD    ;SET SPEED TO EIGHTH SPEED
      STA A    SPEEDA     ;SET UP SPEED VARIABLE FOR USE LATER
      BRA      STOD
      ;
      STOB     CMP A      #004H ;TEST FOR <5 DEG
      BHI      STOC       ;BR TO <10 DEG IS <5 DEG TEST FAILS
      LDA A    #QUASPD    ;SET SPEED TO QUARTER SPEED
      STA A    SPEEDA     ;USED LATER
      BRA      STOD
      STOC     LDA A      AZSPD ;SET SPEED TO USER SELECTED SPEED (MOD 1.3)
      STA A    SPEEDA     ;USED LATER
      STOD     LDA A      AZKEYS ;DESTINATION NOT REACHED, CHECKS SIGNS
      CMP A    AZSIGN
      BEQ      SAMEAZ
      DIFFAZ   CMP A      #02BH ;DIFF SIGNS
      BEQ      B2
      JMP      LEFT
      B2       JMP      RIGHT
      SAMEAZ   CMP A      #02BH ;SAME SIGN FIND WHICH ONE PLUS
      BEQ      YESAZ
      NOAZ     TST      CARRY
      BMI      B3
      JMP      LEFT
      B3       JMP      RIGHT
      YESAZ    TST      CARRY
      BMI      B4
      JMP      RIGHT
      B4       JMP      LEFT
      ;
      ;ELEVATION MOTOR CONTROL LOOP
      ;
      STOE     LDA A      ELKEYS
      CMP A    ELSIGN
      BEQ      STOE
      ; THIS CODE DUPLICATED FROM THE AZ CODE ABOVE

```

```

LDA A    ELKEY+1
ADD A    ELBCD+1
DAA
STA A    ELMAG+1
LDA A    ELKEY
ADC A    ELBCD
DAA
LDA B    ELMAG+1
STA A    ELMAG
BRA      STOY1
STOY     LDX      #ELBCD
LDA A    ELKEY
LDA B    ELKEY+1
JSR      BCDSUB
STA A    ELMAG
STA B    ELMAG+1
;
; ADDED TO TIGHTEN ELEVATION CONTROL LOOP TO .1 DEGREE (MOD 1.1)
;
STOY1    TST A
; THIS CODE ALSO DUPLICATED FROM AZ CODE
BNE      STOZ
CMP B    #10H
BHI      STOZ
LDA A    #OFFH
STA A    SFLAGE
STA A    LSBSEL
JMP      CPFLAG
STOZ     TST A
BNE      STOF
CMP B    #050H
BHI      STOF
LDA A    #ETHSPD
STA A    SPEEDE
BRA      STOH
;
STOF     CMP A    #004H
BHI      STOG
LDA A    #0UASPD
STA A    SPEEDE
BRA      STOH
STOG     LDA A    ELSPD
STA A    SPEEDE
STOH     LDA A    ELKEYS
CMP A    ELSIGN
BEQ      SAMEEL
DIFFEL   CMP A    #02BH
BEQ      B5
BRA      B7
B5       BRA      B8
SAMEEL   CMP A    #02BH
BEQ      YESEL
NOEL     TST      CARRY
BMI      B6
BRA      B7
B6       BRA      B8
YESEL    TST      CARRY
BMI      B7
B8       JMP      UP
B7       JMP      DOWN
;END STATE ZERO
;
; BEGIN STATE 1
;

```

```

ST1      LDA A      #QUASPD ;BEGIN STATE ONE, MANUAL DOWN
        LDA B      #OFFH
        JSR        MOTEL ;JUMPS TO SUBROUTINE COMMAND ELEVATION MOTOR
ST1A     LDA A      #70H
        STA A      DDRA
        LDA A      DDRA
        CMP A      #77H ;HAS DOWN KEY BEEN LET UP YET
        BNE        ST1B ;DOWN KEY IS NOT BEING PRESSED NOW
        JSR        RESTO ;RESTORE KEYBOARD BEFORE READING ANGLES (MOD 1.1)
        JSR        SHAENC ;DOWN KEY NOT UP YET THEREFOR READ ANGLES
        BRA        ST1A
ST1B     CLR        LFLAGE ; CLR LIM REACHED FLG.
        LDA A      #OFFH ;TURN OFF MOTOR
        TAB        ;CLOCKWISE MOTION STILL SET
        JSR        MOTEL
        JSR        RESTO ;RESTORE KEYBOARD PIA, AND BACK TO STATE ZERO
        JMP STO

;=====
;
;                               BEGIN STATE 2
;
;=====
ST2      LDA A      #QUASPD ;BEGIN STATE 2, LOAD A WITH SPEED (MOD 1.2)
        CLR B      ;LOAD B WITH DIRECTION (MOD 1.2)
        JSR        MOTEL
ST2A     LDA A      #70H
        STA A      DDRA
        LDA A      DDRA
        CMP A      #07BH ;KEY RELEASED ?
        BNE        ST2B
        JSR        RESTO ;RESTORE KEYBOARD BEF READING ANGLES
        JSR        SHAENC ;UP KEY STILL BEING PRESSED. READ ANGLES
        BRA        ST2A
ST2B     CLR        LFLAGE ;CLEAR LIMIT REACHED FLAG
        LDA A      #OFFH ;C-CLOCKWISE MOTION SET
        CLR B
        JSR        MOTEL
        JSR        RESTO
        JMP        STO
;END STATE 2

;=====
;
;                               BEGIN STATE 3
;
;=====
ST3      LDA A      #QUASPD ;BEGIN STATE 3. LOAD A WITH SPEED (MOD 1.2)
        CLR B      ;LOAD B WITH DIRECTION (MOD 1.2)
        JSR        MOTAZ ;JMP TO ROUTINE TO COMMAND AZIMUTH MOTOR
ST3A     LDA A      #080H
        STA A      DDRA
        LDA A      DDRA
        CMP A      #087H ;HAS RIGHT KEY BEEN RELEASED?
        BNE        ST3B
        JSR        RESTO
        JSR        SHAENC
        BRA        ST3A
ST3B     CLR        LFLAGE ;CLEAR LIMIT REACHED FLAG (MOD 1.1)
        LDA A      #OFFH ;TURN AS MOTOR OFF
        CLR B
        JSR        MOTAZ
        JSR        RESTO ;RESTORE KEYBOARD PIA. BACK TO STO
        JMP STO
;END STATE 3

```

```

;
; BEGIN STATE 4
;
;
;
;
ST4 LDA A #QUASPD ;BEGIN STATE 4. LOAD A=SPEED (MOD 1.2)
    LDA B #OFFH ;LOAD B WITH DIRECTION
    JSR MOTAZ
ST4A LDA A #OBOH
    STA A DDRA
    LDA A DDRA
    CMP A #OBBH ;HAS LEFT KEY BEEN RELEASED?
    BNE ST4B
    JSR RESTO
    JSR SHAENC
    BRA ST4A
ST4B CLR LFLAGA ;CLEAR LIMIT REACHED FLAG (MOD 1.1)
    LDA A #OFFH
    TAB ;CLOCKWISE MOTION
    JSR MOTAZ
    JSR RESTO
    JMP STO
    ;END STATE FOUR
;
; BEGIN STATE 5
;
;
;
ST5 LDX #MSG4 ;DISPLAYS "ERROR INVALID ENTRY"
    JSR ASCDIS
    LDA B #10
    JSR WAITE
    JMP STO ;BACK TO STATE 0
    ;END STATE 5
;
; BEGIN STATE 6
;
;
;
ST6 LDX #MSG8
    JSR ASCDIS ;DISP "ANGLE TOO LARGE....."
    JMP MSG8 ;WAIT 1 SEC THE RETURN TO CONTROL LOOP
    ;END STATE 6
;
; BEGIN STATE 7
;
;
;
ST7 LDX #MSG11
    JSR ASCDIS ;DISP "POSITIONER HALTED"
    JMP MSG8 ;WAIT 1 SEC THEN RETURN TO CONTROL LOOP
    ;END STATE 7
;
; BEGIN STATE 10
;
;
;
ST10 STA A AZEL ;REMEMBERS WHICH KEY PRESSED (SETAZ OR SETEL)
    LDX #MSG2
    JSR ASCDIS ;DISP "ENTER AZIMUTH ANGLE"
    LDX #DIGEL+1
    STA GAVEY ;KEEPS TRACK OF WHERE THINGS ARE ON THE DISPLAY

```

```

ST10A  LDA A    KFLAG
      BPL      ST10A
      CLR      KFLAG      ;CLEAR KEYENTRY FLAG
      LDX      #MSG6
      JSR      ASCDIS      ;DISPLAY "AZIMUTH"
      CLR      ENTRYA
      CLR      ENTRYB      ;CLEAR BOTH REGS TO BE USED WHEN PACKING ENTRIES
      LDA A    KEYENT      ;GETS KEYENTRY
      LDX      #SP10
      JSR      ADDCAL
      LDX      0,X
      JMP      0,X      ;JUMPS TO NEXT STATE DETERMINED BY KEYENTRY IN A
      ;END STATE 10

```

```

;:
;:
;: BEGIN STATE 11
;:
;:

```

```

ST11   STA A    AZEL      ;REMEMBERS KEY PRESSED (SETEL OR SETAZ)
      LDX      #MSG1
      JSR      ASCDIS      ;DISP "ENTR ELECAION ANGLE"
      LDX      #DISEL+1
      STX      SAVEX
ST11A  LDA A    KFLAG      ;WAITS FOR NEXT ENTRY
      BPL      ST11A
      CLR      KFLAG      ;CLEAR ENTRY FLAG
      LDX      #MSG7
      JSR      ASCDIS      ;DISPLAYS "ELEVATION"
      CLR      ENTRYA
      CLR      ENTRYB
      LDA A    KEYENT      ;GETS KEYENTRY
      LDX      #SP11
      JSR      ADDCAL
      LDX      0,X
      JMP      0,X
      ;END STATE 11

```

```

;:
;:
;: BEGIN STATE 12
;:
;:

```

```

ST12   LDA B    #02BH      ;BEGIN STATE 12, PLUS SIGN AND MAGNITUDE
      LDX      SAVEX
      STA B    0,X      ;DIPLAYS PLUS SIGN
      INX
      STA B    TEMPS      ;INCREMENTS TRACKING POINTING
      LSR A      ;REMEMBERS SIGN OF ENTRY
      TAB      ;CONVERTS KEYCODE TO BCD CODE
      JSR      PACK      ;ROUTINE TO PACK ENTRY
      ADD B    #030H      ;CONVERTS BCD CODE TO ASCII
      STA B    0,X      ;ECHOS KEYENTRY ON THE DISPLAY
      INX
      STX      SAVEX      ;REMEMBERS NEW VALUE OF TRACKING POINTER
ST12A  LDA A    KFLAG      ;WAIT FOR ANOTHER KEYENTRY
      BPL      ST12A
      CLR      KFLAG
      LDA A    KEYENT      ;GETS KEYENTRY
      LDX      #SP12
      JSR      ADDCAL
      LDX      0,X
      JMP      0,X
      ;END STATE 12

```

```

;:
;:

```

```

;;                                     BEGIN STATE 13                                     ;;
;;                                                                                                                                              ;;
;;                                                                                                                                              ;;
ST13      LDA B      #02DH
          LDX         SAVEX
          STA B       0,X          ;DISPLAYS ENTERED MINUS SIGN
          INX         ;INC TRACKING POINTER
          STX         SAVEX      ;SAVE TRACKING POINTER
          STA B       TEMPS
ST13A     LDA A      KFLAG
          BPL         ST13A
          CLR         KFLAG
          LDA A      KEYENT
          LDX         #SP13
          JSR         ADDCAL
          LDX         0,X
          JMP         0,X
          ;END STATE 13

;;                                                                                                                                              ;;
;;                                     BEGIN STATE 14                                     ;;
;;                                                                                                                                              ;;
;;                                                                                                                                              ;;
ST14      LSR A
          TAB
          JSR         PACK          ;ST14 DIPLAYS ENTERED NUM AFTER MINUS SIGN
          ADD B       #030H
          LDX         SAVEX
          STA B       0,X          ;ECHO KEYENTRY
          INX         ;INC TRACKING POINTER
          STX         SAVEX      ;KEEPS TRACK OF POINTER
          LDA A      KFLAG        ;WAITS FOR NEXT KEYENTRY
ST14A     BPL         ST14A
          CLR         KFLAG      ;CLEARS KEYENTRY FLAG
          LDA A      KEYENT      ;GETS KEYENTRY
          LDX         #SP14      ;LOADS INDEX REGISTER WITH STATE 14 POINTER
          JSR         ADDCAL
          LDX         0,X
          JMP         0,X
          ;END STATE 14

;;                                                                                                                                              ;;
;;                                     BEGIN STATE 15                                     ;;
;;                                                                                                                                              ;;
;;                                                                                                                                              ;;
ST15      LSR A
          TAB
          JSR         PACK          ;CONVERTS KEYCODE TO BCD CODE
          ADD B       #030H        ;ST15 DIPLAYS SECOND NUM AFTER EITHER + OR -
          LDX         SAVEX
          STA B       0,X
          INX
          STX         SAVEX
ST15A     LDA A      KFLAG
          BPL         ST15A        ;WAIT FOR NEXT KEYENTRY
          CLR         KFLAG      ;CLEARS KEYENTRY FLAG
          LDA A      KEYENT
          LDX         #SP15
          JSR         ADDCAL
          LDX         0,X
          JMP         0,X
          ;END STATE 15

```



```

;;                                     BEGIN STATE 18                                     ;;
;;                                                                                       ;;
;
ST18      CLR      MFLAG      ;CLEARs MOTOR FLAG: ST18 GO TO CNTRL LOOP
          CLR      LFLAG     ;CLEARs LIMIT REACHED FLAG
          CLR      LFLAG
          JMP      STO
          ;END STATE 18

;
;;                                     BEGIN STATE 19                                     ;;
;;                                                                                       ;;
;
ST19      LDA      A          #OFFH      ;ST19 DISABLES CONTROL LOOP (MOD 1.1)
          STA      A          MFLAG     ;SETs MOTOR FLAG SO CNTRL LOOP DISABLED
          JSR      ALSTOP
          TST      LFLAG     ;CHECK FOR AZ LIMIT REACHED
          BEQ      ST19A     ;GO IF NOT REACHED
          CLR      A          ;AZ LIMIT REACHED
          LDA      B          DFLAG     ;GET CURR DIRECTION STATUS
          COM      B          ;GET OFF DIRECTION
          JSR      MOTAZ
          LDA      B          #10
          JSR      WAITE      ;ALLOW TIME FOR AZ MOTOR TO REPOSITION GIMBAL
          LDA      A          #OFFH
          LDA      B          DFLAG
          JSR      MOTAZ      ;STOP MOTOR, LIMIT NO LONGER EXCEEDED
          JMP      STO
ST19A     CLR      LFLAG
          TST      LFLAG     ;CHECK FOR EL LIMIT REACHED
          BEQ      ST19B     ;GO IF EL LIMIT NOT EXCEEDED
          CLR      A          ;EL LIMIT REACHED
          LDA      B          DFLAG     ;GET CURR DIRECTION
          COM      B          ;GET OFF DIR
          JSR      MOTEL
          LDA      B          #10
          JSR      WAITE      ;WAIT FOR EL MOTOR TO FINISH MOVE
          LDA      A          #OFFH
          LDA      B          DFLAG
          JSR      MOTEL      ;STOP EL MOTOR, LIMIT NO LONGER EXCEEDED
          CLR      LFLAG
          JMP      STO
ST19B     JMP      ST7        ;DISPLAYS "POSITIONER HALTED",WAIT 1 SEC,STO
          ;END STATE 19

;
;;                                     BEGIN STATE 20                                     ;;
;;                                                                                       ;;
;
ST20      LDX      #MSG9
          JSR      ASCDIS     ;DISPLAY "ENTER PROG NUMBER"
          LDX      #DISG+5
          STX      SAVEX
ST20A     LDA      A          KFLAG
          BPL      ST20A     ;WAIT FOR KEYENTRY
          CLR      KFLAG
          CLR      ENTRYA
          CLR      ENTRYB
          LDX      #MSG10
          JSR      ASCDIS     ;DISPLAY "PROG   :ENTER   "
          LDA      A          KEYENT
          LDX      #DIS20
          JSR      ADDCAL

```



```

        STA A      DISEL+5      ;DISPLAYS A "B" AFTER ENTER
        STA A      PROGL        ;STORES PROGRAM LETTER
        JMP        ST21A
ST25B   LDX        ENTRYA
        STX        PROGB
        ;
        ;ADDITION TO ST25B. CKS SEE IF PROG3 BEING IMPL"D
        ;MOD (1.1)
        ;
        LDA B      PROGN
        CMP B      #33H        ;ASCII "3"
        BEQ        ST25A      ;GO IF STATE=PROG 3
        ;
        LDA B      #10
        JSR        WAITE
        LDX        #MSG3      ;CLEAR DIS
        JSR        ASCDIS
        LDX        #MSG10     ;DISPLAY "PROG :ENTER"
        JSR        ASCDIS
        LDA A      PROGN
        STA A      DISAZ+5
        LDA A      #043H      ;DISPLAY "C"
        STA A      DISEL+3
        STA A      PROGL      ;STORES CURR PROG LETTER
        JMP        ST21A      ;JUMPS TO ENTER "C"
ST25C   LDX        ENTRYA
        STX        PROGC
ST25A   LDA A      KFLAG
        BFL        ST25A
        CLR        KFLAG
        LDA A      KEYENT
        LDX        #SP25
        JSR        ADDCAL
        LDX        0.X
        JMP        0.X
        ;END STATE 25
;=====
;;
;;                               BEGIN STATE 00
;;
;
;      ;ST00 (MOD 1.1) PROGRAM DISTRIBUTION STATE
;
ST00    LDA A      PROGN      ;GET PROG NUM
        CMP A      #31H
        BEQ        ST001      ;BR IF IN PROG #1
        CMP A      #32H
        BEQ        ST002      ;BR IF IN PROG #2
        CMP A      #33H
        BEQ        ST003      ;BR IF IN PROG #3
        JMP        ST29      ;GO TO PROG #4
ST001   JMP        ST26      ;GO TO PROG #1
ST002   JMP        ST27      ;GO TO PROG #2
ST003   JMP        ST28      ;GO TO PROG #3
        ;END STATE 00
;=====
;;
;;                               BEGIN STATE 26
;;
;
;      ;ST26 (MOD 1.2) PATTERN NUM ONE
;
ST26    LDX        #0          ;CLEAR X REG
        STX        MFLAG      ;CLEAR MOTOR FAG AND PRGB FLAG

```

	LDX	PROGA	;GETS TWO-BYTE RASTER PARAM "A"
	STX	AZKEY	;ENTERS AZ PART OF FIRST POINT
	LDX	PROGC	
	STX	ELKEY	;SAVE TWO-BYTE ANSWER
	LDX	#2D2BH	;GET ASCII "MINUS" AND "PLUS" VALS FOR SIGNS
	STX	AZKEYS	;ENTER AZ,EL SIGN VALS
	LDX	#ST26A	
	STX	STADDR	;SAVES RETURN ADDRESS
	CLR	PROCNT	;CLEARS PROGRAM STATE COUNTER
	DEC	PFLAG	
	JMP	STO	;SETS PROG FLAG,GO TO CNTRL LOOP,ANTICIPATE RETURN
ST26A	LDA B	#02BH	
	STA B	AZKEYS	;ENTER #2 POINT IN RASTER
	LDA B	ELSIGN	;GET CURR EL SIGN VAL
	CMP B	#2BH	;IS POSOTIONER ABOVE AZ AXIS
	BEQ	ST26A1	;BR IF HAS RASTER IS NOT DONE
	LDA A	ELBCD	;GET CURR EL POSITION
	LDA B	ELBCD+1	
	LDX	#PROGC	;X REG POINTS TO DESTINATION
	JSR	BCDSUB	; (CURR EL POS)-(DEST)
	CMP A	#1	;CK PROXIMITY IF POSITIONER TO TERMINATION POINT
	BHI	WEIRD	;ABSOLUTE MAG > 1.XX DEG
WEIRD	BRA	DONE	;POSITIONER WITHIN TERMINATIN RANGE. STOP
	TST	CARRY	;CK IF PAST POINT
	BMI	ST26A1	;RASTER STILL WORKING DO NOT STOP
DONE	LDX	#ST26D	;DEST REACHED, STOP RASTER
	BRA	ST26A2	
ST26A1	LDX	#ST26B	;RASTER NOT FINISHED, GOTO NEXT POINT
ST26A2	STX	STADDR	;SAVE RETURN ADDRESS
	INC	PROCNT	;INC PROGRAM COUNTER
	JMP	STO	;GO TO CONTROL LOOP, ANTICIPATE RETURN
ST26B	LDA B	ELSIGN	;GET CURR EL SIGN
	CMP B	#2BH	;HAS POS CROSSED AZ AXIS?
	BEQ	ST26B0	;GO IF STILL ABOVE AXIS
	LDA A	ELKEY+1	;CROSSED AXIS MUST COMPENSATE
	ADD A	PROGB+1	; (CURR EL)+(INCREMENTAL ANGLE)
	DAA		
	TAB		;SAVES LS INFO IN ACCB
	LDA A	ELKEY	
	ADC A	PROGB	
	DAA		
	BRA	ST26B01	;BR TO ENTER EL CO-ORDINATE
ST26B0	LDA A	ELKEY	;CALC POINT #3
	LDA B	ELKEY+1	;GET CURR EL POS
	LDX	#PROGB	;GET ENTERED INC ANGLE
	JSR	BCDSUB	
ST26B01	STA A	ELKEY	;ENTER IS THIRD POINT
	STA B	ELKEY+1	
	TST	CARRY	;HAS POSITIONER CROSSED AZ AXIS?
	BEQ	ST26B1	;BR IF NOT CROSSED AXIS
	LDA A	#2DH	;ONCE CHANGED TO MINUS, WILL STAY MINUS
	STA A	ELKEYS	;CHANGES EL SIGN TO MINUS AT CROSSING
ST26B1	LDA B	PROCNT	;GETS CURRENT VAL OF PROG COUNTER
	CMP B	#3	;IS PERIOD OF SCAN COMPLETED
	BEQ	ST26B2	;BR IF PERIOD NOT COMPLETE
	LDX	#ST26C	;PERIOD OF SCAN WILL BE COMPLETE
	INC	PROCNT	
	BRA	ST26B3	
ST26B2	LDX	#ST26A	;RET TO SECOND POINT
	CLR	PROCNT	;CLEARS PROCNT,START SCAN OVER
ST26B3	STX	STADDR	;SAVE RETURN ADDRESS
	JMP	STO	;GO CNTRL LOOP, ANTICIPATE RETURN
ST26C	LDA B	#2DH	;ENTER POINT 4
	STA B	AZKEYS	;REVERSE SIGN OF AZ POSITION
	LDX	#ST26B	;RETURN FOR POINT 3 INSTRUCTIONS
	STX	STADDR	;SAVE RETURN ADDRESS

```

        INC      PROCNT      ;INC PROGRAM COUNTER
        JMP      STO
ST26D   CLR      PFLAG      ;CLEAR PROGRAM FLAG
        JMP      ST7         ;DISPLAY"POSITIONER HALTED"
                                ;GO TO CONTROL LOOP AND DO NOT COME BACK
        ;END STATE 26
;=====
;
;                               BEGIN STATE 27
;=====
;
;ST27-PATTERN #2
;
ST27     LDX      #0
        STX      MFLAG      ;THIS CODE SAME AS ABOVE
        LDX      PROGA
        STX      AZKEY
        LDX      PROGC
        STX      ELKEY
        LDX      #2D2BH
        STX      AZKEYS
        LDX      #ST27A
        STX      STADDR
        CLR      PROCNT
        DEC      PFLAG
        JMP      STO
ST27A     LDA B      #02DH
        STA B      ELKEYS
        LDA B      AZSIGN
        CMP R      #2DH
        BEQ      ST27A1
        LDA A      AZBCD
        LDA B      AZBCD+1
        LDX      #PROGC
        JSR      BCDSUB
        CMP A      #1
        BHI      WEIRD1
        BRA      DONE1
WEIRD1   TST      CARRY
        BMI      ST27A1
DONE1    LDX      #ST27D
        BRA      ST27A2
ST27A1   LDX      #ST27B
ST27A2   STX      STADDR
        INC      PROCNT
        JMP      STO
ST27B     LDA B      AZSIGN
        CMP B      #2DH
        BEQ      ST27B0
        LDA A      AZKEY+1
        ADD A      PROGB+1
        DAA
        TAB
        LDA A      AZKEY
        ADC A      PROGB
        DAA
        BRA      ST27B01
ST27B0   LDA A      AZKEY
        LDA B      AZKEY+1
        LDX      #PROGB      ;GET ENTERED INC COUNTER
        JSR      BCDSUB
ST27B01  STA A      AZKEY      ;ENTER IN THIRD POINT
        STA B      AZKEY+1
        TST      CARRY
        BEQ      ST27B1

```

	LDA B	#2BH
	STA B	AZKEYS
ST27B1	LDA B	PROCNT
	CMP B	#3
	BEQ	ST27B2
	LDX	#ST27C
	INC	PROCNT
	BRA	ST27B3
ST27B2	CLR	PROCNT
	LDX	#ST27A
ST27B3	STX	STADDR
	JMP	STO
ST27C	LDA B	#2BH
	STA B	ELKEYS
	LDX	#ST27B
	STX	STADDR
	INC	PROCNT
	JMP	STO
ST27D	CLR	PFLAG
	JMP	ST7
	;END STATE 27	


```

        JSR      MOVED      ;FIX LAST ENTRY IN DECIMAL PT
        LDX      #ST30B
        STX      STADDR    ;STORE RETURN ADDRESS
ST30A   LDA A     IFLAG
        BPL      ST30A
        CLR      KFLAG
        LDA A     KEYENT
        LDX      #SP30
        JSR      ADDCAL
        LDX      0,X
        JMP      0,X
ST30B   LDX      ENTRYA
        STX      NELLIM
        BRA      ST30A
        ;END STATE 30
;=====
;
;                               BEGIN STATE 31
;=====
;
;      ;ST31-SET POS EL LIMITS (MOD 1.1)
;
ST31    LDX      #MSG17
        JSR      ASCDIS    ;DISPLAY "POS EL LIMIT"
        LDX      #DISEL+6
        STX      SAVEX
        LDA A     FELLIM    ;GET POS EL LIMIT
        LDA B     FELLIM+1
        JSR      BCDDIS
        JSR      MOVED
        LDX      #ST31B
        STX      STADDR
ST31A   LDA A     KFLAG
        BPL      ST31A
        CLR      KFLAG
        LDA A     KEYENT
        LDX      #SP31
        JSR      ADDCAL
        LDX      0,X
        JMP      0,X
ST31B   LDX      ENTRYA
        STX      FELLIM
        BRA      ST31A
        ;END STATE 31
;=====
;
;                               BEGIN STATE 32
;=====
;
;      ;ST32-SET NEG AZIMUTH LIMIT
;
ST32    LDX      #MSG18
        JSR      ASCDIS    ;DISPLAY "NEG AZ LIMIT "
        LDX      #DISEL+6
        STX      SAVEX
        LDA A     NAZLIM    ;GET POS AZ LIMIT
        LDA B     NAZLIM+1
        JSR      BCDDIS
        JSR      MOVED
        LDX      #ST32B
        STX      STADDR
ST32A   LDA A     IFLAG
        BPL      ST32A
        CLR      KFLAG

```

```

        LDA A      KEYENT
        LDX        #SF32
        JSR        ADDCAL
        LDX        0,X
        JMP        0,X
ST32B   LDX        ENTRYA
        STX        NAZLIM      ;UPDATE NEGATIVE AZIMUTH LIMIT
        BRA        ST32A
        ;END STATE 32
;=====
;
;                               BEGIN STATE 33
;=====
;
;      ;ST33-SET POSITIVE AZIMUTH LIMIT (MOD 1.1)
;
ST33    LDX        #MSG19
        JSR        ASCDIS      ;DISPLAY "POS AZ LIMIT"
        LDX        #DISL+6
        STX        SAVEX
        LDA A      PAZLIM
        LDA B      PAZLIM+1
        JSR        BCDDIS      ;DISPLAY CURRENT POS AZ LIMIT
        JSR        MOVED
        LDX        #ST33B
        STX        STADDR
ST33A   LDA A      KFLAG
        BPL        ST33A
        CLR        KFLAG
        LDA A      KEYENT
        LDX        #SF33
        JSR        ADDCAL
        LDX        0,X
        JMP        0,X
ST33B   LDX        ENTRYA
        STX        PAZLIM
        BRA        ST33A
        ;END STATE 33
;=====
;
;                               BEGIN STATE 34
;=====
;
;      ;ST34-INPUT NUMBERS FOR SETTING LIMITS--1ST
;
ST34    LSR A
        TAB
        JSR        PACK        ;PACKS BCD INPUT INTO PACKED BCD FORM
        ADD B      #30H        ;CONVERT TO ASCII #
        LDX        SAVEX
        STA B      0,X
        INX
;      ;INC TRACKING POINTER
        STX        SAVEX
ST34A   LDA A      KFLAG
        BPL        ST34A
        CLR        KFLAG
        LDA A      KEYENT
        LDX        #SF34
        JSR        ADDCAL
        LDX        0,X
        JMP        0,X
        ;END STATE 34
;=====
;
;                               BEGIN STATE 35
;=====

```

```

;ST35-INPUT BCD NUMBER--2ND
;
ST35   LSR A           ;CONVERT KEYCODE TO BCD CODE
      TAB
      JSR             PACK
      ADD B           #30H
      LDX             SAVEX
      STA B           0,X
      INX
      STX             SAVEX
ST35A  LDA A           KFLAG
      BPL             ST35A
      CLR             KFLAG
      LDA A           KEYENT
      LDX             #SP35
      JSR             ADDCAL
      LDX             0,X
      JMP             0,X
;END STATE 35

;=====
; BEGIN STATE 36
;=====
;ST36-INPUT DECIMAL POINT
;
ST36   LDA B           #2EH           ;CONVERT INPUT TO BCD CODE
      LDX             SAVEX
      STA B           0,X
      INX
      STX             SAVEX
ST36A  LDA A           KFLAG
      BPL             ST36A
      CLR             KFLAG
      LDA A           KEYENT
      LDX             #SP36
      JSR             ADDCAL
      LDX             0,X
      JMP             0,X
;END STATE 36

;=====
; BEGIN STATE 37
;=====
;ST37-INPUT LAST BCD CHARACTER--3RD
;
ST37   LSR A           ;CONVERT INPUT KEYCODE TO BCD CODE
      TAB
      JSR             PACK
      ADD B           #30H
      LDX             SAVEX
      STA B           0,X
ST37A  LDA A           ENTRYA
      LDA B           ENTRYB
      JSR             TSTANG         ;TEST FOR ANGLE LIMIT CONDITION
      LDX             STADDR
      JMP             0,X
;END STATE 37

;=====
; BEGIN STATE 38
;=====
;ST38-SET AZ GIMBAL SPEED
;
ST38   LDY             #MSG21
      JSR             ASCDIS         ;DISPLAY 'AZ GIMBAL SPEED'
      LDY             #MSG19

```

```

        STA      SAVEX
        LDA A    AZSPEED ;GET LAST USER SELECTED GIMBAL SPEED
        STA A    0,X
        LDX      #ST38B
        STX      STADDR ;SAVES RETURN ADDRESS
ST38A   LDA A    KFLAG
        BPL      ST38A
        CLR      KFLAG
        LDA A    KEYENT
        LDX      #SP38
        JSR      ADDCAL
        LDX      0,X
        JMP      0,X
ST38B   LDA B    SPEED ;GET USER SET GIM SPEED (ASCII)
        STA B    AZSPEED ;SAVE AZ GIM SPEED
        LDA B    GIMSPEED ;GT HEX FORM OF GIM SPEED
        STA B    AZSPD ;SAVE HEX FORM OF GIMBAL SPEED
        BRA      ST38A ;GO BACK TO WAIT FOR ANOTHER KEYENTRY
        ;END STATE 38
;=====
;; BEGIN STATE 39
;=====
;
        ;ST39-SET EL GIMBAL SPEED (MOD 1.3)
;
ST39    LDX      #MSG22
        JSR      ASCDIS ;DISPLAY "EL GIMBAL SPEED"
        LDX      #DISEL+8
        STX      SAVEX
        LDA A    ELSPEED ;GET LAST USER SELECTED GIMBAL SPEED
        STA A    0,X
        LDX      #ST39B
        STX      STADDR
ST39A   LDA A    KFLAG
        BPL      ST39A
        CLR      KFLAG
        LDA A    KEYENT
        LDX      #SP39
        JSR      ADDCAL
        LDX      0,X
        JMP      0,X
ST39B   LDA B    SPEED ;GET USER SEL GIM SPD (ASCII)
        STA B    ELSPEED ;SAVE EL GIM SPEED
        LDA B    GIMSPEED ;GET HEX FORM OF GIM SPD
        STA B    ELSPD ;SAVE HEX FORM OF GIM SPD
        BRA      ST39A
        ;END STATE 39
;=====
;; BEGIN STATE 40
;=====
;
        ;ST40-INPUT SINGLE DIGIT GIMBAL SPEED (MOD 1.3)
;
ST40    LSR A      ;CONVERT KEYCODE TO 0-9
        TAB
        ADD B      #30H
        LDX      SAVEX
        STA B      0,X
        STA B      SPEED
        LDX      #SPDTB
        JSR      ADDCAL
        LDA B      0,X
        STA B      GIMSPEED
        LDX      STADDR
        JMP      0,X
        ;END STATE 40

```



```

;; RETURNS WITH PACKED INFO IN SPEC LOCATION AND IN ACCA,ACCB ;;
;; THE LEAST 4 MS DECIMAL VALS WILL BE CONTAINED IN THE PACKED BCD ANS;;
;
BINBCDED STX      SAVEX      ;SAVE DATA POINTER
          LDX      #K10K      ;INITS X-REG FOR 1ST BCD CONV CONST
          CLR      ENTRY1
          CLR      ENTRY2
ZVDEC1   CLR      SAVEA      ;CLEAR BCD CONVERSION COUNTER
ZVDEC2   SUB B     1,X
          SBC A     0,X
          BCS      ZVDEC5     ;BR IF SUB PRODUCES OVERFLOW
          INC      SAVEA      ;DEC CHAR BEING BUILT, INC SAVEA
          BRA      ZVDEC2
ZVDEC5   ADD B     1,X
          ADC A     0,X      ;RESTORES PARTIAL RESULT UPON OVERFLOW
          PSH      A          ;SAVE ACCA
          LDA A     SAVEA      ;GETS BCD CONVERSION COUNTER
          BSR      PACKED     ;PACKS NEWLY FORMED BCD CHARACTER
          PUL A      ;RESTORES ACCA TO FORMER VALUE
          INX
          INX
          CPX      #K10K+10   ;TESTS TO SEE IF LAST CONSTANT HAS BEEN USED
          BNE      ZVDEC1
          LDA A     ENTRY1     ;LAST CHARACTER HAS BEEN REACHED
          LDA B     ENTRY2
          LDX      SAVEX
          STA A     0,X
          STA B     1,X      ;SAVES 16
          RTS
          ;END BINBCDED SUBROUTINE
;
; "PACKED" SUBROUTINE
; PACKS BINARY NUMBER INTO BCD FORM
; ACCA SHOULD CONTAIN THE UNPACKED BCD FORM
; ROUTINE DESTROYS CONTENTS OF ACCA
;
;
PACKED   ASL      ENTRY2     ;ONE BIT LEFT SHIFT WITH ZERO FIL
          ROL      ENTRY1
          ASL      ENTRY2
          ROL      ENTRY1
          ASL      ENTRY2
          ROL      ENTRY1
          ASL      ENTRY2
          ROL      ENTRY1     ;SHIFTS 16 BIT BINARY INFO OVER ONE CHAR
          ADD A     ENTRY2
          STA A     ENTRY2     ;ENTRY2 FORM="X0",PACKS ANOTHER UNPACKED FORM
          RTS          ;RETURN FORM SUBROUTINE
          ;END PACKED
;
; "BINFPT" SUBROUTINE
; CONVERSION OF FRACTIONAL PART OF BINARY NUM TO PACKED BCD
; LOAD FRACTIONAL PART IN ACCA BEFORE EXECUTING
; ACCB IS USED IN CALCULATION
; ROUTINE EXITS WITH BCD ANSWER (4 DEC PLACES) IN ACCA,ACCB
;
;
BINFPT   STX      SAVEX      ;SAVES DATA POINTER
          STA A     SAVEA      ;SAVE FRACT PART
          STA B     SAVEB      ;(MOD 1.4)
          LDA B     #16        ;(MOD 1.4)
          STA B     SAVEC      ;SAVE BIT COUNTER (MOD 1.4)
          LDX      #CONST      ;SET POINTER IN ACCX AT FIRST BYTE OF CONSTANTS
          CLR A

```

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BIN1    CLR B
        STA A    TEMPA    ;SAVE ACCA TEMPORARILY
        ASL      SAVEB    ;LOOK AT NEXT BIT
        ROL      SAVEA
        BCC      BIN2    ;BR PAST LOOP IF C=0
        TBA      ;OUT ACCB INTO ACCA
        ADD A     1,X      ;C=1, ADD IN CONSTANT
        DAA
        TAB
        LDA A     TEMPA    ;RETRIEVE ACCA FROM TEMP STORAGE
        ADC A     0,X
        DAA
BIN2    INX      ;INC ACCX TO NEXT CONSTANT
        INX
        DEC      SAVEC    ;DEC BIT COUNTER
        BNE      BIN1    ;BR THRU LOOP UNTIL 8 BITS ARE SHIFTED
        LDX      SAVEX    ;RETRIEVE DATA POINTER
        STA A     0,X      ;SAVE 16 BIT PACKED BCD CHARACTE
        STA B     1,X
        RTS      ;RET FROM SUBROUTINE
;=====
; "DIVID100" SUBROUTINE
; DIVIDES BCD VAL BY 100
; ENTRY: ACCA,ACCB CONTAIN 16 BIT BCD NUMBER
; EXIT : ACCA,ACCB CONTAIN 16 BIT BCD RESULT
;=====
DIVID100 TAB      ;THROWS AWAY THE FRACTIONAL PART
        CLR A      ;ACCA,ACCB="00XX"
        RTS      ;RETURN FROM SUBROUTINE
;END DIVID100
;=====
; "CHSIGN" SUBROUTINE
; CHANGES THE SIGN OF A TWO BYTE COORD FROM ONE STATE
; TO THE OTHER
; ENTRY: ACCB CONTAINS SIGN INFO,X REG POINTS TO LOCATION OF
; SIGN INFO
; EXIT : ORIGINAL SIGN INFO AUTOMATICALLY CHANGED,ACCB DESTROYED
;=====
CHSIGN    CMP B     #2BH    ;FIND OUT SIGN
        BEQ      CHSIGN1   ;BR IF PLUS
        LDA B     #2BH    ;SIGN IS MINUS
        BRA      CHSIGN2
CHSIGN1   LDA B     #2DH    ;CH PLUS TO MINUS
CHSIGN2   STA B     0,X      ;UPDATE SIGN VAL
        RTS      ;RETURN
;END CHSIGN
;=====
; "CONSIGN" SUBROUTINE
; GETS SIGN OF 32 BIT FP # AND FINDS ASCII EQUIV
; ENTRY: ACCB CONTAINS SIGN PORTION OF FP #
; X REG CONTAINS LOCATION OF RESULTING SIGN
; EXIT : APPROPRIATE SIGN IS LOCATED, ACCB DESTROYED
;=====
CONSIGN   BMI      CONSIGN1 ;BR IF NEG
        LDA B     #2BH    ;SIGN IS PLUS ASCII = 2BH
        BRA      CONSIGN2
CONSIGN1  LDA B     #2DH    ;SIGN IS MINUS ASCII IS 2DH
CONSIGN2  STA B     0,X      ;UPDATE SIGN VAL
        RTS      ;RETURN
;END CONSIGN
;=====
; "TRGVALUE" SUBROUTINE - SIN,COS OF BINARY ANGLE
; ENTRY: ACCB=# BYTES, X-REG POINTS TO ADDR OF BIN ANGLE
;=====

```



```

;;      EXIT : 2 BYTE VAL AZKEY AND ELKEY ARE REPLACED, ACCB DESTROYED ;;
;;      ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

```

```

TRGVALUE LDA B      #2H      ;ACCB=#BYTE TO BE PUT AT TOS
BSR      PUSH      ;PUSH ANGLE ONTO APU STACK
BSR      FLTS      ;CONVERT ANG TO 32 BIT FLT PT FORM
LDX      #RADIANS   ;X-REG POINTS TO PI/180 CONST
LDA B      #4H
BSR      PUSH
BSR      FMUL      ;BIN ANG * PI/180 = ANGLE IN RADIANS RESULT TOS
BSR      PTOF      ;DUP BIN ANGLE AT NOS
BSR      COS       ;TAKE COS OF ANGLE
LDX      #RADIUS    ;X-REG POINT TO RADIUS 16 BIT FIXED POINT
LDA B      #2H
BSR      PUSH
BSR      FLTS      ;CONVERT RADIUS TO 32 BIT FL PT #
BSR      PTOF      ;PUSH 32 BIT TOS TO NOS
BSR      POPF      ;32 BIT APU STACK POP
BSR      FMUL      ;RADIUS*COS(ANG)= ELEVATION
LDX      #FPT32
LDA B      #4H
BSR      PULL      ;PULL ELEVATION FROM APU STACK
LDX      #ELRESULT  ;X POINTS TO LOCATION OF RESULT
JSR      FPTBCD     ;CONVERT 32 BIT FP TO 4 BYTE BCD RESULT
BSR      SIN
BSR      FMUL      ;RADIUS*SIN(ANG)=AZ
LDX      #FPT32
LDA B      #4H
BSR      PULL
LDX      #AZRESULT  ;X-REG POINTS TO RESULT
JSR      FPTBCD     ;CONVERT 32 BIT FP TO 4 BYTE BCD RESULT
LDX      #ELKEYS
LDA B      #ELRESULT ;GET 1ST BYTE OF RESULT
BSR      CONSIGN   ;CONVERTS FP SIGN TO ASCII VAL
LDX      #AZKEYS
LDA B      #AZRESULT
BSR      CONSIGN
LDX      #ELRESULT
LDA A      2,X      ;GET MSBYTE OF MAG VAL OF FPT
LDA B      3,X      ;GET LSBYTE OF MAG VAL OF FPT
STA A      ELKEY    ;UPDATE EL COORD
STA B      ELKEY+1
LDX      #AZRESULT
LDA A      2,X      ;GET MAG VAL OF FPT
LDA B      3,X
STA A      AZKEY
STA B      AZKEY+1
RTS
;END TRGVALUE

```

```

;;      ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
;;      "PUSH" SUBROUTINE - MOVES B BYTES OF DATA ONTO APU STACK ;;
;;      ENTRY: ACCB CONTAINS # BYTES TO PUSH ONTO STACK ;;
;;      ACCX CONTAINS ADDRESS OF MSBYTE OF DATA TO PUSH ;;
;;      EXIT : DATA WILL BE PLACED ON APU STACK SUCH THAT MSB OF ;;
;;      WILL BE TOS. X-REG DESTROYED , ACCB DESTROYED ;;
;;      ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

```

```

PUSH      PSH      B      ;SAVES THE NUMBER OF BYTES
PUSH1     INX
DEC B
BNE      PUSH1      ;BR THRU TILL LAST BYTE REACHED
STX      TEMPX
PUL B
PUSH2     DEX      ;RETRIEVES # BYTES TO BE PUSHED
LDA A      0,X      ;ACCESS NEXT ADD TO PUT ONTO APU STACK
STA A      APUDATA  ;ENTER CURR BYTE OF DATA ONTO APU STACK

```

```

        DEC B
        BNE     PUSH2
        LDX     TEMPX
        RTS
        ;END PUSH
;=====
; "FLTS" SUBROUTINE
; CONVERT 16 BIT FIX PT TO 32 BIT FP
; ENTRY: 16 FIXED # ON TOS
; EXIT : WHEN APU FINISHED
;=====
FLTS     LDA B     #1DH      ;LOADS IN FLOAT OPCODE
        BRA      TSTEND    ;WAIT TILL APU FINE
;=====
; "PTOF" SUBROUTINE
; DUP TOS AT NOS
; ENTRY: 32 BIT FP # AT TOS
; EXIT : WHEN APU FINISHED
;=====
PTOF     LDA B     #17H
        BRA      TSTEND
;
; COS SUBROUTINE
; 32 BIT FLOATING COSINE
; ENTRY: 32 BIT FP AT TOS
; EXIT : WHEN APU DONE
;
COS       LDA B     #3H      ;LOAD IN COS COMMAND
        BRA      TSTEND
;
; "POPF" SUBROUTINE - POP NOS INTO TOS
; ENTRY: 32 BIT FP # AT TOS
; EXIT : WHEN APU DONE
;
POPF     LDA B     #18H
        BRA      TSTEND
;
; "FMUL" SUBROUTINE - 32 BIT FLOATING POINT MULTIPLIER
; ENTRY: 2 #S ON TOS AND NOS
; EXIT : WHEN APU DONE
;
FMUL     LDA B     #12H
        BRA      TSTEND
;
; "PULL" SUB - REMOVES B BYTES OF DATA FROM THE STACK
; ENTRY: ACCB = # BYTES TO BE PULLED
; ACCX = ADDRESS TO WHERE TOS TO BE PLACED
; EXIT : WHEN DONE
;
PULL     LDA A     APUDATA
        STA A     0,X
        INX
        DEC B
        BNE     PULL
        RTS
;
; "SIN" SUB - 32 BIT FP SIN
; ENTRY: 32 BIT FP AT TOS
; EXIT : WHEN DONE
;
SIN      LDA B     #2H
        BRA      TSTEND
;
; "XCHF" SUB - EXCH 32 BIT OPERANDS TOS AND NOS

```

```

; ENTRY: BOTH #'S MUST BE ON APU STACK BEFORE XCH
; EXIT : WHEN DONE
XCHF    LDA B    #19H
        BRA      TSTEND

; "FADD" SUB - 32 BIT FLOATING POINT ADDITION
; ENTRY: BOTH #'S ON STACK
FADD    LDA B    #10H
        BRA TSTEND

; "FSUB" SUBROUTINE - 32 BIT FP SUBTRACT
; ENTRY: BOTH #'S ON TOS AND NOS
; EXIT : RESULT ON TOS
FSUB    LDA B    #11H
        BRA      TSTEND

; "FDIV" SUB- DIVIDE 2 32 BIT FP #'S
; NOS/TOS
; ENTRY: 2 32-BIT #'S ON NOS AND TOS
FDIV    LDA B    #13H
        BRA      TSTEND

; "TSTEND" SUBROUTINE - LOOPS UNTIL ENDFLAG FROM APU LOW (PA7 OF PIA2)
; ENTRY: ISSUE COMMAND TO APU
; EXIT : WHEN APU DONE
TSTEND  STA B     APUSTAT ; ISSUES COMM TO APU
TSTEND1 LDA A     DDRA3   ; CK ENDFLAG
        BPL      TSTEND1 ; LOOP TILL LOW
        LDA A     APUSTAT ; CLEAR FLAG
        RTS

; "RESTO" SUBROUTINE - RETURNS THE KEYBOARD TO AN INITIALIZED STATE
; SO THAT ANY KEY PRESSED WILL GENERATE AN INTERRUPT
RESTO   LDA A     #0FH
        STA A     DDRA   ; RESTORE THE ROWS OF KBD FOR NXT KEY PUSHED
        LDA A     DDRA   ; CLEAR IRQ BITS IN CRA
        LDA A     #0FFH
        STA A     MFLAG  ; DIS CONTROL LOOP
        RTS

; "MOVED" SUBROUTINE - INSERTS A DECIMAL POINT IN FRONT OF LAST
; BCD CHARACTER (USED IN ST30-33)
MOVED   LDA A     DISEL+8
        LDA B     #2EH
        STA B     DISEL+8
        STA A     DISEL+9
        RTS

; "CPFLAG" SUBROUTINE - (MOD 1.1)
CPFLAG  LDA A     3FLAGA
        CMP A     #0FFH
        BNE      CP1
        TST      PFLAG ; LOOKS AT PROGRAM FLAG
        BEQ      CP1   ; BR TO CNTRL LOOP IF NOT IN PROGRAMMED SEQ
        LDX      STADDR ; YES, A PROGRAMMED SEQ CURRENTLY IN OPERATION
        JMP      0,X    ; JMPS BACK TO THE PROGRAMMED CONTROL LOOP
CP1      JMP      STO    ; PROGRAM FLAG CLEARED, GOTO CNTRL LP

; "TSTANG" SUBROUTINE

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```

;
; COMPARES THE TWO ACCX'S WITH THE CONTENTS OF THE
; INDEX REGISTER. RETURNS FROM SUB IF CONTENTS OF
; INDEX REGISTER ARE > THE CONTENTS OF THE ACCX'S
; BRANCHES TO ERROR 6 IF NOT
;
TSTANG LDX #LIMIT
        JSR BCDSUB
        TST CARRY
        BMI NOPE
        JMP ST6 ;BR IF ENTERED ANGLE EXCEEDS LIMIT OF +/- 40.0
NOPE    RTS

;
; "BCDBIN" SUBROUTINE
; CONVERTS FOUR BINARY CODED DECIMAL DIGIT
; TO A BINARY EQUIVALENT. THE BCD DIGITS ARE PACKED
; TWO PER BYTE. THE BINARY RESULT OCCUPIES TWO BYTES
; THE BCD DIGITS ARE LOADED INTO THE ACCA AND ACCB
; (MSD-ACCA) AND THE BCDBIN SUBROUTINE IS CALLED.
; THE ROUTINE EXITS WITH THE BINARY RESULT IN ACCA
; AND ACCB (MOD 1.1)
;
BCDBIN STA A SAVE1 ;SAVE 2 BCD VALS
        CLR BINUPR
        TBA
        AND B #0FH ;SAVE ONLY LS BCD VAL
        LSR A
        LSR A
        LSR A
        LSR A
TENLP   BEQ DOHUND ;GO DOHUND WHEN TEN IS ZERO
        ADD B #10 ;ADD 10 TO BINARY TOTAL
        DEC A ;DEC TENS DIGIT AND
        BRA TENLP ;REPEAT UNTIL 0
DOHUND  CLC
        LDA A SAVE1 ;GET HUN IN THOU DIGIT
        AND A #0FH ;SAVE ONLY HUN DIGIT
HUNLP   BEQ DOTHOU ;DO THOU IF HUN IS 0
        ADD B #100 ;ADD 100 TO BINARY VAL
        BCC HUN00
        INC BINUPR ;ADD 256 TO BINARY UPPER VAL
HUN00   DEC A ;DEC HUN DIGIT ONE
        BRA HUNLP ;REPEAT TIL 0
DOTHOU  LDA A SAVE1 ;GET THOU DIGIT
        LSR A
        LSR A
        LSR A
        LSR A
        STA A SAVE1 ;SAVE THOU DIGIT
        BNE THOU00 ;BR IF THOU DIGIT = 0
        LDA A BINUPR ;GET BIN UPPER VAL
        BRA XITBIN
THOU00  LDA A BINUPR ;GET BIN UPPER VALUE
THOULP  CLC ;RESET CARRY
        ADD B #232 ;ADD 232 TO BINARY LOWER
        ADC A #3H ;ADD 768 TO BINARY UPPER
        DEC SAVE1 ;DEC THOU DIGIT
        BNE THOULP ;REPEAT TILL THOU DIGIT = 0
XITBIN  RTS

;
; "PACK" SUBROUTINE
; PACKS BINARY #'S INTO BCD FORM
; ACCA=UNPACKED BCD FORM
; DESTROYS ACCA
;
PACK    ADD A ENTRYB ;ENTRYB LOOKS LIKE "X0"
        STA A ENTRYB ;PACKS IN ANOTHER BCD FORM

```

```

        ASL      ENTRYB
        ROL      ENTRYA
        ASL      ENTRYB
        ROL      ENTRYA
        ASL      ENTRYB
        ROL      ENTRYA
        ASL      ENTRYB
        ROL      ENTRYA
        RTS

;
; "ALSTOP" SUBROUTINE
; ROUTINE THAT STOPS BOTH MOTORS FOR EXCEEDING ANGLE LIMIT
;
ALSTOP  LDA A      #OFFH
        STA A      LSBGAZ ;STOPS AZ MOTOR
        STA A      LSBSEL ;STOPS EL MOTOR
        RTS

;
; "BCDSUB" SUBROUTINE
; SUBTRACT 2 16-BIT BCD PACKED #'S
; SUBTRACTS INDEXED ADDRESS FROM ACCA,ACCB
; INDEX REG CONTAINS STARTING ADDRESS
; ACCA,ACCB CONTAINS # TO BE SUBTRACTED FROM
; RETURN RESULT IN ACCA,ACCB
;
; *****
; *          9999          *
; *      -IXRG            *
; *      -----          *
; *      DIFF             *
; *      + 1              *
; *      -----          *
; *      DIFF+1           *
; *      + BCD#           *
; *      -----          *
; *      ANSWER           *
; * *****
;
; BCS TSTS OV CONDITION
; BCC TSTS NO OV CONDITION
;
BCDSUB  CLR      CARRY    ;RESET CARRY VALUE
        CMP A      0,X    ;IS CONTENTS OF ACCA BIGGER ?
        BHI      SUBT    ;BR IF MINUEND>SUBTRAHEND
        BNE      SWAP    ;BR IF MIN<>SUBTRAHEND
        CMP B      1,X    ;MSBYTE OF MIN=MSBYTE OF SUBTRAHEND
        BHI      SUBT    ;MIN>SUBTRAHEND
        BEQ      SUBT    ;MIN=SUBTRAHEND OK TO SUBTRACT AS IS
        SWAP     PSH B    ;SAVE MIN TEMPORARILY
        PSH A
        DEC      CARRY    ;SET CARRY BYTE TO DENOTE OV
        LDA A      0,X    ;GET SUBTRAHEND
        LDA B      1,X
        TSX
        STA A      TEMPB  ;X REG POINTS TO MINUEND
        STA B      TEMPB  ;SUBTRACT SMALLER FR GREATER
        LDA A      #099H  ;SAVE GREATER OF 2 #'S
        TAB
        SUB A      1,X    ;ACCB=99
        SUB B      0,X    ;RESULT => ACCA,ACCB "9999"
        SEC        ;SUBTRACT SMALLER NUM FROM 9999
        ADC A      TEMPB  ;LS BYTE OF DIFF+LSBYTE OF GREATER NUM +1
        DAA
        PSH A        ;SAVE LS BYTE OF RESULT
        TBA        ;MOVE MSBYTE OF DIFF INTO ACCA
        ADC A      TEMPB  ;MSBYTE OF DIFF+ MSBYTE OF > # + CARRY BIT

```

```

DAA
PUL B
TST CARRY ; RETRIEVE LS BYTE OF RESULT
BEQ BACK ; ACCA,ACCB=RESULT OF BCD SUBTRACT
INS ; IF NO OV NO NEED CLEAN STACK
INS ; CLEAN UP STACK
BACK RTS

;
; "SHAENC" SUBROUTINE
; READS SHAFT ANGLE ENCODERS
;
SHAENC LDA A MSBSAZ ; READS AZIMUTH ANGLE
LDA B LSBSAZ
STA A MSBENC ; STORES ANGLE IN TEMP LOC
STA B LSBENC
ASL B ; SCALE DAC OUTPUT BY FACTOR OF 2
ROL A
STA A DDRA2 ; OUTPUT MS 4 BITS OF AZ TO DAC
STA B DDRB2 ; " LS " " " " "
LDA A MSBENC ; GET OLD A AND B
LDA B LSBENC
LDX #DIVISO
JSR DIVIDE ; DIVIDES ANGLE BY 14,912
LDX #AZBCD
JSR BINBCD
PSH A
PSH B

;
; ADDITION OF SHAENC SUBROUTINE - CK + AND - AZ LIMITS
;
STA B TEMPB ; SAVES ACCB TEMPO
LDA B SIGN ; START LIM CK
CMP B #2BH
BEQ PAL ; BR IF AZ COORD +
LDA B TEMPB ; AZ COORDS -
LDX #NAZLIM
JSR BCDSUB ; ACCX-NAZLIM
LDA A CARRY
BNE SHA2 ; BR IF ACCX>NAZLIM
PAL1 LDA B #OFFH ; POSITIONER EXCEEDED LIMIT
STA B LFLAGA ; SET AZ LIMIT FLAG
LDX #MSG15
JSR ASCDIS ; DISPLAY "ANGLE LIMIT EXCEEDED"
JSR ALSTOP ; BR TO STOP BOTH MOTORS
JMP MSGB ; WAIT 1 SEC AND GO CNTRL LP
PAL LDA B TEMPB ; CK FOR + AZ LIMIT
LDX #PAZLIM ; GET + AZ LIMIT
JSR BCDSUB ; ACCX-PAZLIM
LDA A CARRY
BEQ PAL1
SHA2 LDA A SIGN
STA A AZSIGN
LDA A #041H
STA A LETA
LDA A #05AH
STA A LETB
FUL B
FUL A
LDX #ANGLE
JSR BCDDIS ; UPACK BCD ANGLE
LDX #DISAZ
JSR ASC2 ; DISPLAYS PACKED BCD ON PANEL
LDA A MSBSEL ; READS EL ANGLE
LDA B LSBSEL
STA A MSBENC ; STORE ANGLE TEMPORARILY
STA B LSBENC

```

ASL B		
ROL A		
STA A	DDRA3	; OUTPUT MS 4 BITS OF EL TO DAC
STA B	DDR3	; OUTPUT LS 4 BITS OF EL TO DAC
LDA A	MSBENC	; GET OLD A AND B
LDA B	LSBENC	
LDX	#DIVISO	
JSR	DIVIDE	; DIVIDE ANGLE BY 14,912
LDX	#ELBCD	
JSR	BINBCD	; RET PACKED BCD #
PSH A		
PSH B		
STA B	TEMPB	; HANDLES CHANGE IN COORD SYSTEM
LDA B	SIGN	

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